

Geometric Theory of Parabolic Problems

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Problem. Abstract parabolic **evolution equation** in Banach space under **time discretisation**

$$u' = F(u) \quad \xrightarrow[\text{discretisation}]{\text{time}} \quad \frac{u_{n+1} - u_n}{h} = F(u_{n+1}).$$

Classical approach. Constant $C(T)$ in **error bound**

$$\|u_n - u(nh)\| \leq C(T)h, \quad 0 \leq nh \leq T,$$

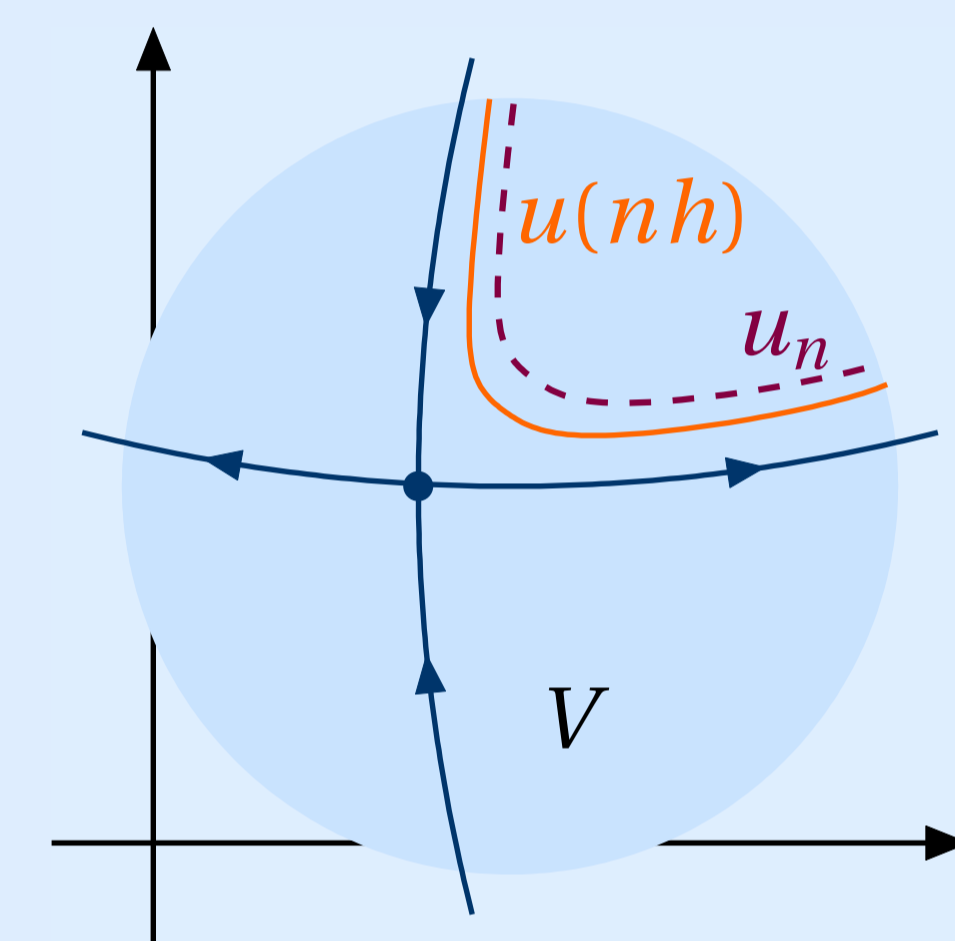
in general grows exponentially with time T .

Geometric theory. Analyse **qualitative properties** of continuous and corresponding **discrete dynamical system**.

Study **invariant objects** and discrete analogues.

- ◇ Equilibrium points, Periodic solutions
- ◇ Invariant manifolds, Bifurcations, etc.

Are **stability properties** captured by discretisation?



Saddle point. Study stable and unstable manifolds under discretisation.

Theorem. **Error bound** with constant C only depending on V

$$\|u_n - u(nh)\| \leq Ch, \quad 0 \leq nh \leq T.$$

Numerical solution is **shadowed** by a true solution.

Problem classes.

- ◇ Non-autonomous problems
- ◇ Semilinear problems
- ◇ Fully nonlinear problems

Method classes.

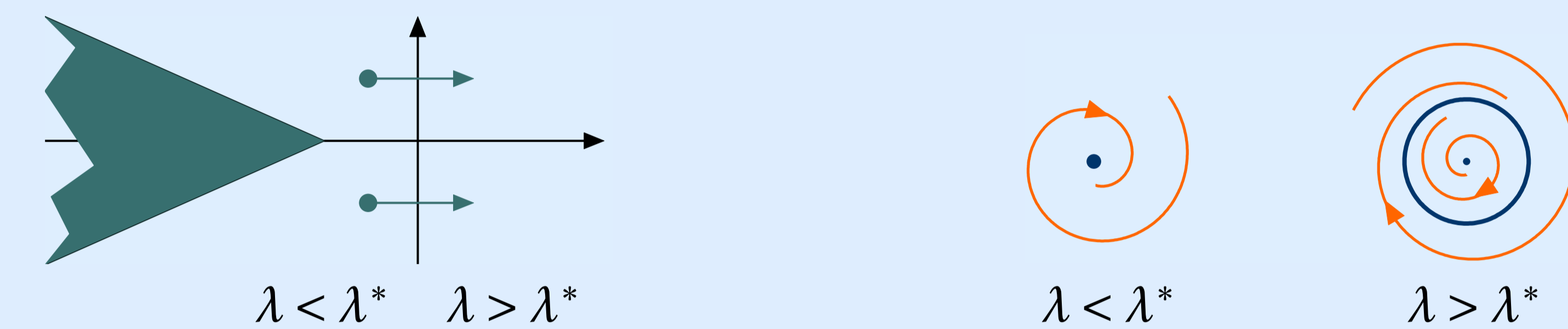
- ◇ Implicit Runge-Kutta methods
- ◇ Implicit multistep methods
- ◇ Linearly-implicit methods

Hopf bifurcation. **Parameter-dependent** parabolic equation

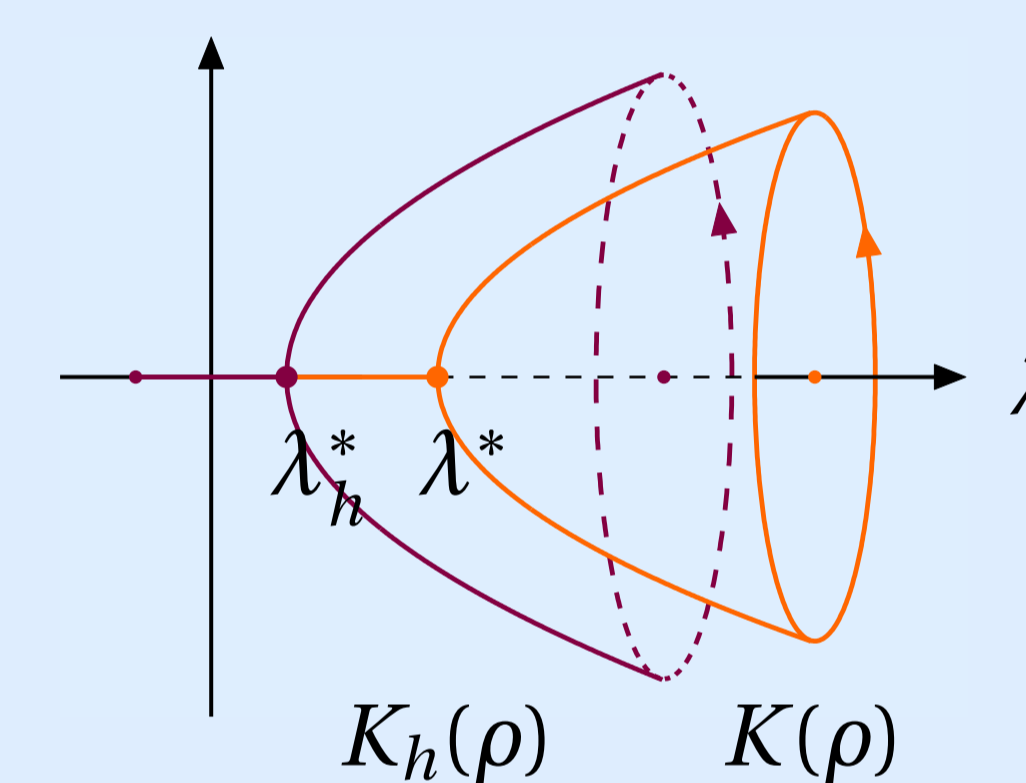
$$u' + A(\lambda)u = f(u, \lambda)$$

with **equilibrium** u^* , i.e., u^* satisfies $A(\lambda)u^* = f(u^*, \lambda)$.

Spectral assumption on $D_u f(u^*, \lambda) - A(\lambda)$



yields generically **supercritical** Hopf bifurcation at $\lambda = \lambda^*$.



Define parameter ρ by

$$\lambda = \lambda^* + \rho^2$$

$$\lambda_h = \lambda_h^* + \rho^2$$

Theorem. Any strongly $A(\vartheta)$ -stable Runge-Kutta discretisation of order p and stage order q possesses a **Naimark-Sacker bifurcation** at λ_h^* for h sufficiently small. Further, the relations

$$|\lambda_h^* - \lambda^*| \leq Ch^p, \quad \text{dist}_V(K(\rho), K_h(\rho)) \leq C\rho h^r$$

are valid with $r = \min(p, q + 1)$.

Example. Incompressible **Navier-Stokes equations** in 2D and 3D

$$u' - \lambda \Delta u = -(u \cdot \nabla)u - \nabla p, \quad \text{div } u = 0.$$



Selected references.

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