

# Favourable time integration methods for non-autonomous evolution equations

Mechthild Thalhammer

Numerical methods for PDEs and their applications  
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# Contents and related work

## Contents.

- **Commutator-free quasi-Magnus (CFQM) exponential integrators for non-autonomous linear evolution equations**  
Appropriate name thanks to Arieh Iserles
- **Splitting methods for nonlinear autonomous evolution equations**  
Possibility of local error control with negligible additional cost
- CFQM exponential integrators combined with splitting methods for non-autonomous nonlinear evolution equations

## Focus in this talk.

- Joint work with SERGIO BLANES and FERNANDO CASAS.

## Related work.

- With WINFRIED AUZINGER, KARSTEN HELD, OTHMAR KOCH.
- With ERIKA HAUSENBLAS.

# First remarks on commutator-free quasi-Magnus exponential integrators for linear evolution equations

## Areas of application

**Situation.** Consider non-autonomous linear evolution equation

$$u'(t) = A(t) u(t), \quad t \in (t_0, T).$$

### Areas of application.

◇ Linear evolution equations of Schrödinger type

Linear Schrödinger equations involving space-time-dependent potential

Quantum systems

Models for oxide solar cells (with W. AUZINGER, K. HELD, O. KOCH)

◇ Linear evolution equations of parabolic type

Variational equations related to diffusion-advection-reaction equations

Dissipative quantum systems

Rosen–Zener models with dissipation

**Remark.** Abstract formulation helps to recognise common structure of complex processes.

# Commutator-free quasi-Magnus exponential integrators

**Issue.** **Exact solution** of non-autonomous linear evolution equation **not available** (used only theoretically as ideal case)

$$u'(t) = A(t) u(t), \quad t \in (t_0, T).$$

**Remark.** In autonomous case, solution (formally) given by exponential

$$w'(t) = A_0 w(t), \quad w(t_0 + \tau) = e^{\tau A_0} w(t_0).$$

**Approach.** In non-autonomous case, compute numerical approximation (time stepsize  $\tau > 0$ , second-order scheme)

$$\mathcal{S}(\tau) u(t_0) \approx u(t_0 + \tau), \quad \mathcal{S}(\tau) = e^{\tau A(t_0 + \frac{\tau}{2})}.$$

Desirable to use higher-order approximations (favourable in efficiency).  
Study class of **commutator-free quasi-Magnus exponential integrators**

$$\mathcal{S}(\tau) = e^{\tau B_J(\tau)} \dots e^{\tau B_1(\tau)}, \quad B_j(\tau) = \sum_{k=1}^K a_{jk} A(t_n + c_k \tau).$$

**Secret of success.** *Smart choice of arising coefficients.*

# References

## Our background.

Previous work on **design** of higher-order commutator-free quasi-Magnus exponential integrators.

S. BLANES, P. C. MOAN. *Fourth- and sixth-order commutator-free Magnus integrators for linear and non-linear dynamical systems*. Applied Numerical Mathematics 56 (2006) 1519–1537.

S. BLANES, F. CASAS, J. A. OTEO, J. ROS. *The Magnus expansion and some of its applications*. Phys. Rep. 470 (2009) 151–238.

Previous work on stability and error **analysis** of fourth-order scheme for parabolic equations. Explanation of **order reductions** due to imposed homogeneous Dirichlet boundary conditions.

M. TH. *A fourth-order commutator-free exponential integrator for nonautonomous differential equations*. SIAM Journal on Numerical Analysis 44/2 (2006) 851–864.

# References

## Our main inspiration.

**Application** of commutator-free quasi-Magnus exponential integrators in quantum dynamics.

A. ALVERMANN, H. FEHSKE. *High-order commutator-free exponential time-propagation of driven quantum systems*. Journal of Computational Physics 230 (2011) 5930–5956.

A. ALVERMANN, H. FEHSKE, P. B. LITTLEWOOD. *Numerical time propagation of quantum systems in radiation fields*. New Journal of Physics 14 (2012) 105008.

# Complete the big picture ...

## Main objectives.

- **Stability and error analysis** of commutator-free quasi-Magnus exponential integrators and related methods for different classes of evolution equations
  - Evolution equations of parabolic type  
SERGIO BLANES, FERNANDO CASAS, M. TH. *Convergence analysis of high-order commutator-free quasi-Magnus exponential integrators for non-autonomous linear evolution equations of parabolic type*. IMA J. Numer. Anal. (2017).
  - Evolution equations of Schrödinger type  
Time-dependent Hamiltonian ( $A(t) = i\Delta + iV(t)$ , e.g.)
- **Design of efficient schemes**  
SERGIO BLANES, FERNANDO CASAS, M. TH. *High-order commutator-free quasi-Magnus exponential integrators and related methods for non-autonomous linear evolution equations*. Submitted.



## First illustration (Parabolic equation)

*Practice in numerical methods is the only way of learning it.*

H. Jeffreys, B. Jeffreys

**Test equation.** Consider nonlinear diffusion-advection-reaction equation

$$\partial_t U(x, t) = f_2(U(x, t)) \partial_{xx} U(x, t) + f_1(U(x, t)) \partial_x U(x, t) + f_0(U(x, t)) + g(x, t).$$

Associated **variational equation** has form of non-autonomous linear evolution equation

$$\partial_t u(x, t) = \alpha_2(x, t) \partial_{xx} u(x, t) + \alpha_1(x, t) \partial_x u(x, t) + \alpha_0(x, t) u(x, t).$$

Impose periodic boundary conditions and regular initial condition.

# First illustration (Parabolic equation)

**Test equation.** Consider non-autonomous linear evolution equation

$$\partial_t u(x, t) = \alpha_2(x, t) \partial_{xx} u(x, t) + \alpha_1(x, t) \partial_x u(x, t) + \alpha_0(x, t) u(x, t).$$

Impose periodic boundary conditions and regular initial condition.

**Special choice.** In particular, set

$$(x, t) \in \Omega \times [0, T], \quad \Omega = [0, 1], \quad T = 1,$$

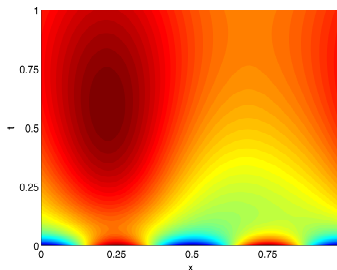
$$U(x, t) = e^{-t} \sin(2\pi x), \quad u(x, 0) = (\sin(2\pi x))^2,$$

$$f_2(w) = \frac{1}{10} \left( \cos(w) + \frac{11}{10} \right), \quad f_1(w) = \frac{1}{10} w,$$

$$f_0(w) = w \left( w - \frac{1}{2} \right),$$

$$\alpha_2(x, t) = f_2(U(x, t)), \quad \alpha_1(x, t) = f_1(U(x, t)),$$

$$\alpha_0(x, t) = f_2'(U(x, t)) \partial_{xx} U(x, t) \\ + f_1'(U(x, t)) \partial_x U(x, t) + f_0'(U(x, t)).$$



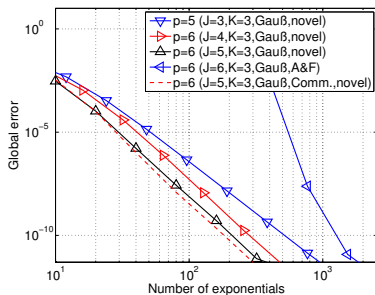
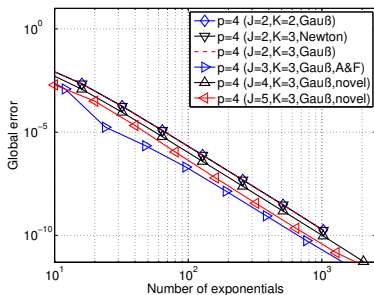
## First illustration (Parabolic equation)

*One must watch the convergence of a numerical code as carefully as a father watching his four year old play near a busy road.* J. P. Boyd

**Time integration.** Apply commutator-free quasi-Magnus exponential integrators and related method of non-stiff orders  $p = 4, 5, 6$ . Choose spatial grid width sufficiently small such that temporal error dominates.

- ◇ Determine global errors versus number of exponentials (efficiency).  
More appropriate indicator for efficiency used for Rosen–Zener model. Improved performance of novel schemes.

# First illustration (Parabolic equation)



## Observations.

- ◇ Commutator-free integrators retain nonstiff orders of convergence.
- ◇ Poor stability of high-order schemes found in literature (e.g. 6th-order scheme by ALVERMANN, FEHSKE).

# Further remarks

**Magnus versus commutator-free quasi-Magnus exponential integrators**  
**Approach to resolve stability issues**

# Magnus expansion

**Magnus expansion (Magnus, 1954).** Formal representation of solution to non-autonomous linear evolution equation based on **Magnus expansion**

$$\begin{cases} u'(t) = A(t) u(t), & t \in (t_0, T), \\ u(t_0) \text{ given,} \end{cases}$$

$$u(t_n + \tau_n) = e^{\Omega(\tau_n, t_n)} u(t_n), \quad t_0 \leq t_n < t_n + \tau_n \leq T,$$

$$\begin{aligned} \Omega(\tau_n, t_n) = & \int_{t_n}^{t_n + \tau_n} A(\sigma) d\sigma \\ & + \frac{1}{2} \int_{t_n}^{t_n + \tau_n} \int_{t_n}^{\sigma_1} [A(\sigma_1), A(\sigma_2)] d\sigma_2 d\sigma_1 \\ & + \frac{1}{6} \int_{t_n}^{t_n + \tau_n} \int_{t_n}^{\sigma_1} \int_{t_n}^{\sigma_2} \left( [A(\sigma_1), [A(\sigma_2), A(\sigma_3)]] \right. \\ & \left. + [A(\sigma_3), [A(\sigma_2), A(\sigma_1)]] \right) d\sigma_3 d\sigma_2 d\sigma_1 + \dots \end{aligned}$$

# Magnus integrators

**Magnus integrators.** Truncation of Magnus expansion and application of quadrature formulae for approximation of multiple integrals leads to class of (interpolatory) **Magnus integrators**.

- ◇ Second-order Magnus integrator (exponential midpoint rule)

$$\tau_n A\left(t_n + \frac{\tau_n}{2}\right) \approx \Omega(\tau_n, t_n).$$

- ◇ Fourth-order Magnus integrator, see BLANES, CASAS, ROS (2000)

$$\frac{1}{6} \tau_n \left( A(t_n) + 4A\left(t_n + \frac{\tau_n}{2}\right) + A(t_n + \tau_n) \right) - \frac{1}{12} \tau_n^2 [A(t_n), A(t_n + \tau_n)] \\ \approx \Omega(\tau_n, t_n).$$

**Issue.** Presence of iterated commutators.

# Magnus-type integrators

**Disadvantages.** Presence of **iterated commutators** causes

- **loss of structure** (issues of well-definedness and stability for PDEs involving differential operators).
- possibly high **computational cost** (for realisation of action of arising matrix-exponentials on vectors by Krylov-type methods, e.g.).

**Alternative.** **Commutator-free quasi-Magnus exponential integrators** provide useful alternative to interpolatory Magnus integrators.

A. ALVERMANN, H. FEHSKE, P. B. LITTLEWOOD.

*Numerical time propagation of quantum systems in radiation fields.*  
*New Journal of Physics* 14 (2012) 105008.

*... We explain the use of commutator-free exponential time propagators for the numerical solution of the associated Schrödinger or master equations with a time-dependent Hamilton operator. These time propagators are based on the Magnus series but avoid the computation of commutators, which makes them suitable for the efficient propagation of systems with a large number of degrees of freedom. ...*



# Commutator-free quasi-Magnus exponential integrators

**Situation.** Consider non-autonomous linear evolution equation

$$\begin{cases} u'(t) = A(t) u(t), & t \in (t_0, T), \\ u(t_0) \text{ given.} \end{cases}$$

Use time-stepping approach, i.e., determine approximations at certain time grid points  $t_0 < t_1 < \dots < t_N \leq T$  by recurrence

$$\begin{aligned} u_{n+1} &= \mathcal{S}(\tau_n, t_n) u_n \approx u(t_{n+1}) = \mathcal{E}(\tau_n, t_n) u(t_n), \\ \tau_n &= t_{n+1} - t_n, \quad n \in \{0, 1, \dots, N-1\}. \end{aligned}$$

**General format.** Cast high-order commutator-free quasi-Magnus exponential integrators into general form

$$\begin{aligned} \mathcal{S}(\tau_n, t_n) &= e^{\tau_n B_{nJ}} \dots e^{\tau_n B_{n1}}, \\ B_{nj} &= \sum_{k=1}^K a_{jk} A_{nk}, \quad A_{nk} = A(t_n + c_k \tau_n). \end{aligned}$$

# Commutator-free quasi-Magnus exponential integrators

**General format.** Recall general format

$$\mathcal{S}(\tau_n, t_n) = e^{\tau_n B_{nJ}} \dots e^{\tau_n B_{n1}},$$
$$B_{nj} = \sum_{k=1}^K a_{jk} A_{nk}, \quad A_{nk} = A(t_n + c_k \tau_n).$$

**Remark.** Commutator-free quasi-Magnus exponential integrators generalise **time-splitting methods** defined by coefficients  $(\alpha_\ell, \beta_\ell)_{\ell=1}^S$  (freeze time by adding differential equation  $\frac{d}{dt} t = 1$ )

$$u_{n+1} = e^{\tau_n \alpha_s A_{ns}} \dots e^{\tau_n \alpha_1 A_{n1}} u_n, \quad c_k = \sum_{\ell=1}^k \beta_\ell,$$

with the merit of a significantly reduced number of exponentials, which enhances efficiency.

Examples (Nonstiff orders  $p = 4, 6$ )

**Order 4.** Fourth-order method based on **two Gaussian quadrature nodes** requires evaluation of **two exponentials** at each time step

$$p = 4, \quad J = 2 = K, \quad c_k = \frac{1}{2} \mp \frac{\sqrt{3}}{6}, \quad a_{1k} = \frac{1}{4} \pm \frac{\sqrt{3}}{6},$$
$$\mathcal{L}(\tau_n, t_n) = e^{\tau_n(a_{21}A_{n1} + a_{22}A_{n2})} e^{\tau_n(a_{11}A_{n1} + a_{12}A_{n2})}.$$

Scheme suitable for evolution equations of **Schrödinger type** and of **parabolic type**, since

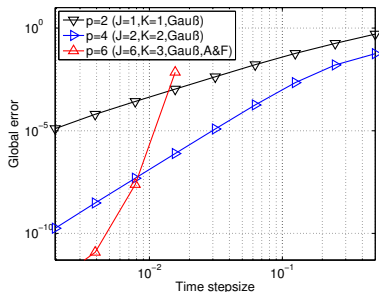
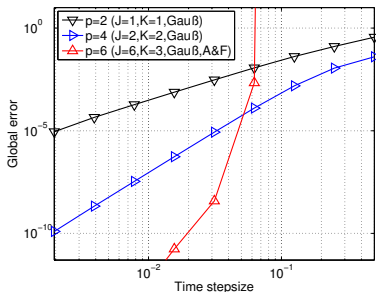
$$b_1 = a_{11} + a_{12} = \frac{1}{2} = a_{21} + a_{22} = b_2.$$

**Order 6.** Sixth-order method obtained from coefficients given in ALVERMANN, FEHSKE. Scheme suitable for evolution equations of **Schrödinger type**, but **poor stability behaviour** observed for evolution equations of **parabolic type**, since

$$\exists j \in \{1, \dots, J\}: \quad b_j = \sum_{k=1}^K a_{jk} < 0.$$

# Counter-example

**Numerical experiment.** Apply commutator-free quasi-Magnus exponential integrators of nonstiff orders  $p = 2, 4, 6$  to parabolic test equation (see before). Display global errors versus time stepsizes for  $M = 50$  (left) and  $M = 100$  (right) space grid points. Sixth-order scheme shows **poor stability behaviour**.



# First conclusions

## First conclusions.

- ◇ **Order barrier** at order four, i.e. commutator-free quasi-Magnus exponential integrators of order five or higher necessarily involve **negative coefficients** which cause integration backward in time (ill-posed problem).
- ◇ Close connexion to class of time-splitting methods gives reasons for the study of *unconventional* commutator-free quasi-Magnus exponential integrators involving **complex coefficients** under additional **positivity condition**.

# Convergence result

# Analytical framework

**Analytical framework.** Suitable functional analytical framework for evolution equations of Schrödinger or parabolic type based on

- ◇ selfadjoint operators and unitary evolution operators on Hilbert spaces or
- ◇ sectorial operators and analytic semigroups on Banach spaces.

**Hypotheses (Parabolic case).** Domain of  $A(t) : D \subset X \rightarrow X$  time-independent, dense and continuously embedded. Linear operator  $A(t) : D \subset X \rightarrow X$  sectorial, uniformly in  $t \in [t_0, T]$ , i.e., there exist  $a \in \mathbb{R}$ ,  $0 < \phi < \frac{\pi}{2}$ ,  $C_1 > 0$  such that

$$\|(\lambda I - A(t))^{-1}\|_{X \leftarrow X} \leq \frac{C_1}{|\lambda - a|}, \quad t \in [t_0, T], \quad \lambda \notin S_\phi(a) = \{a\} \cup \{\mu \in \mathbb{C} : |\arg(a - \mu)| \leq \phi\}.$$

Graph norm of  $A(t)$  and norm in  $D$  equivalent for  $t \in [t_0, T]$ , i.e., there exists  $C_2 > 0$  such that

$$C_2^{-1} \|x\|_D \leq \|x\|_X + \|A(t)x\|_X \leq C_2 \|x\|_D, \quad t \in [t_0, T], \quad x \in D.$$

Defining operator family is Hölder-continuous for some exponent  $\vartheta \in (0, 1]$ , i.e., there exists  $C_3 > 0$  such that

$$\|A(t) - A(s)\|_{X \leftarrow D} \leq C_3 |t - s|^\vartheta, \quad s, t \in [t_0, T].$$

**Consequence.** Sectorial operator  $A(t)$  generates analytic semigroup  $(e^{\sigma A(t)})_{\sigma \in [0, \infty)}$  on  $X$ .  
 By integral formula of Cauchy, representation follows

$$e^{\sigma A(t)} = \frac{1}{2\pi i} \int_{\Gamma} e^{\lambda} (\lambda I - \sigma A(t))^{-1} d\lambda, \quad \sigma > 0, \quad e^{\sigma A(t)} = I, \quad \sigma = 0.$$

# Basic assumptions on methods

**Commutator-free quasi-Magnus exponential integrators.** High-order commutator-free quasi-Magnus exponential integrators cast into general form

$$\mathcal{S}(\tau_n, t_n) = e^{\tau_n B_n J} \dots e^{\tau_n B_n 1}, \quad B_{nj} = \sum_{k=1}^K a_{jk} A_{nk}, \quad A_{nk} = A(t_n + c_k \tau_n).$$

Employ standard assumption that ratios of **subsequent time stepsizes** remain bounded

$$\varrho_{\min} \leq \frac{\tau_{n+1}}{\tau_n} \leq \varrho_{\max}, \quad n \in \{0, 1, \dots, N-2\}.$$

**Nodes and coefficients.** Relate nodes to **quadrature nodes** and suppose

$$0 \leq c_1 < \dots < c_K \leq 1.$$

Assume basic **consistency condition** to be satisfied (direct consequence of elementary requirement  $\mathcal{S}(\tau_n, t_n) = e^{\tau_n A}$  for time-independent operator  $A$ )

$$\sum_{j=1}^J b_j = 1, \quad b_j = \sum_{k=1}^K a_{jk}, \quad j \in \{1, \dots, J\}.$$

In connection with evolution equations of **parabolic type** employ **positivity condition**, which ensures **well-definedness** of commutator-free quasi-Magnus exponential integrators within analytical framework of sectorial operators and analytic semigroups

$$\Re b_j > 0, \quad j \in \{1, \dots, J\}.$$



# Convergence result

## Situation.

- ◇ Employ standard hypotheses on operator family defining **non-autonomous linear evolution equation of parabolic or Schrödinger type**.  
See BLANES, CASAS, TH. (parabolic case) and draft (Schrödinger case, special structure).
- ◇ Use that coefficients of considered high-order **CFQM exponential integrator** fulfill basic assumptions (**positivity condition for parabolic case**) and order conditions.

## Theorem

*Provided that operator family and exact solution are sufficiently regular, following estimate holds in underlying Banach space with constant  $C > 0$  independent of  $n \in \{0, 1, \dots, N\}$  and time increments  $0 < \tau_n \leq \tau_{\max}$*

$$\|u_n - u(t_n)\|_X \leq C \left( \|u_0 - u(t_0)\|_X + \tau_{\max}^p \right).$$

**Crucial point.** Specify **regularity and compatibility requirements on exact solution**.

- ◇ Test equation: For  $X = \mathcal{C}(\Omega, \mathbb{R})$  obtain regularity requirement  $u(t) \in \mathcal{C}^{2p}(\Omega, \mathbb{R})$ .
- ◇ Schrödinger equation with  $A(t) = i\Delta + iV(t)$ : For  $X = L^2(\Omega, \mathbb{C})$  weaker assumption  $\partial_x^{p-1} u(t) \in L^2(\Omega, \mathbb{C})$  sufficient.

# Main tools of proof

**Stability.** Relate stability function of commutator-free quasi-Magnus exponential integrator to analytic semigroup (suitable choice of frozen time  $t$ )

$$\Delta_{n_0}^n = \prod_{i=n_0}^n \mathcal{S}_i(\tau_i, t_i) - e^{(t_{n+1}-t_{n_0})A(t)}, \quad \|e^{sA(t)}\|_{X \leftarrow X} + s \|e^{sA(t)}\|_{D \leftarrow X} \leq C.$$

Employ telescopic identity, bounds for analytic semigroup, Hölder-continuity of defining operator family, and Gronwall-type inequality to deduce desired stability bound

$$\left\| \prod_{i=n_0}^n \mathcal{S}_i(\tau_i, t_i) \right\|_{X \leftarrow X} \leq C.$$

**Local error.** Repeated application of variation-of-constants formula yields **suitable representation** which is starting point for further expansions

$$u(t_{n+1}) - \mathcal{S}(\tau_n, t_n) u(t_n) = \sum_{j=1}^J \sum_{k=1}^K a_{jk} \left( \prod_{i=j+1}^J e^{\tau_n B_{ni}(\tau_n)} \right) \int_0^{\tau_n} e^{(\tau_n - \sigma) B_{nj}(\tau_n)} g_{njk}(\sigma) d\sigma,$$

$$g_{njk}(\sigma) = (A(t_n + d_{j-1}\tau_n + b_j\sigma) - A(t_n + c_k\tau_n)) u(t_n + d_{j-1}\tau_n + b_j\sigma).$$

Resulting local error representation involved for high-order schemes.

# Design of novel schemes

## Numerical comparisons for dissipative quantum system

# Derivation of order conditions

## Approach.

- ◇ Focus on design of efficient schemes of non-stiff orders  $p = 4, 5$  involving  $K = 3$  Gaussian quadrature nodes. By time-symmetry of schemes achieve  $p = 6$ .
- ◇ Employ **advantageous reformulation** (suffices to study first time step, indicate dependence on time stepsize  $\tau > 0$ )

$$\prod_{j=1}^J e^{\tau(a_{j1}A_1(\tau)+a_{j2}A_2(\tau)+a_{j3}A_3(\tau))} = \prod_{j=1}^J e^{x_{j1}\alpha_1(\tau)+x_{j2}\alpha_2(\tau)+x_{j3}\alpha_3(\tau)} + \mathcal{O}(\tau^{p+1}), \quad \alpha_k(\tau) = \mathcal{O}(\tau^k).$$

- ◇ Determine **set of independent order conditions** (obtain  $q = 10$  conditions for  $p = 5$ , use Lyndon multi-index (1, 2) and corresponding word  $\alpha_1\alpha_2$  etc.)

$$(1): y_j = \sum_{\ell=1}^J x_{\ell 1} = 1, \quad (2): z_j = \sum_{\ell=1}^J x_{\ell 2} = 0, \quad (3): \sum_{j=1}^J x_{j3} = \frac{1}{12},$$

$$(1,2): \sum_{j=1}^J x_{j2}(x_{j1} + 2y_{j-1}) = -\frac{1}{6}, \quad (1,3): \sum_{j=1}^J x_{j3}(x_{j1} + 2y_{j-1}) = \frac{1}{12}, \quad (2,3): \sum_{j=1}^J x_{j3}(x_{j2} + 2z_{j-1}) = \frac{1}{120},$$

$$(1,1,2): \sum_{j=1}^J x_{j2}(x_{j1}^2 + 3y_{j-1}^2 + 3x_{j1}y_{j-1}) = -\frac{1}{4}, \quad (1,1,3): \sum_{j=1}^J x_{j3}(x_{j1}^2 + 3y_{j-1}^2 + 3x_{j1}y_{j-1}) = \frac{1}{10},$$

$$(1,2,2): \sum_{j=1}^J x_{j1}(x_{j2}^2 - 3x_{j2}z_j + 3z_j^2) = \frac{1}{40}, \quad (1,1,1,2): \sum_{j=1}^J x_{j2}(x_{j1}^3 + 4y_{j-1}^3 + 6x_{j1}y_{j-1}^2 + 4x_{j1}^2y_{j-1}) = \frac{3}{10}.$$

# Design of novel schemes

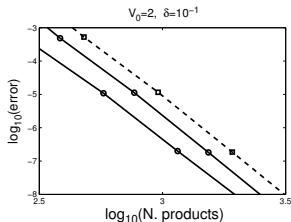
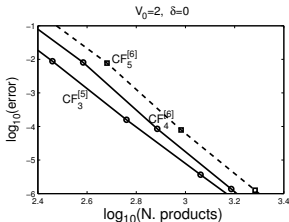
## Additional practical constraints.

- ◇ In certain cases, require **time-symmetry** to further reduce number of order conditions (for  $p = 6$  obtain  $q = 7$  conditions (1), (3), (1,2), (2,3), (1,1,3), (1,2,2), (1,1,1,2))

$$\Psi_J^{[r]}(-\tau) = (\Psi_J^{[r]}(\tau))^{-1}, \quad x_{J+1-j,k} = (-1)^{k+1} x_{jk}.$$

- ◇ In certain cases, express solutions to order conditions in terms of few coefficients and **minimise** amount by which high-order conditions (e.g. at order seven) are not satisfied.

**Favourable novel schemes.** Illustrate favourable behaviour of resulting novel schemes for dissipative quantum system (Rosen-Zener model). Display results for schemes of order  $p = 5, 6$  with complex coefficients satisfying positivity condition.



**Observations.** Schemes remain stable for  $\delta > 0$ . Scheme with  $J = 3$  favourable in efficiency.

# Remarks on operator splitting methods for nonlinear evolution equations

Possibility of local error control with negligible additional cost

# Splitting methods

**Situation.** Consider autonomous linear evolution equation of form

$$\begin{cases} u'(t) = A u(t) + B u(t), & t \in (0, T), \\ u(0) = u_0. \end{cases}$$

**Approach.** Apply  $p$ th-order splitting method involving  $s$  compositions

$$u_{n+1} = e^{b_s \tau_n B} e^{a_s \tau_n A} \dots e^{b_1 \tau_n B} e^{a_1 \tau_n A} u_n \approx u(t_{n+1}) = e^{\tau_n (A+B)} u(t_n).$$

Realisation straightforward

$$u = u_n$$

for  $j = 1 : s$

$$u = e^{a_j \tau_n A} u$$

$$u = e^{b_j \tau_n B} u$$

end

$$u_{n+1} = u$$

# Basic approach for local error estimation

**Approach for local error estimation.** For instance, consider splitting method by BLANES, MOAN or splitting method by YOSHIDA (complex coefficients, melt two subsequent time steps), where

$$p = 4, \quad s = 7.$$

Auxiliary third-order approximation obtained by suitable linear combination of intermediate values used for local error estimation

$$u = u_n, \quad u_{\text{Estimator}} = \alpha_0 u$$

for  $j = 1 : s$

$$u = e^{a_j \tau_n A} u, \quad u_{\text{Estimator}} = u_{\text{Estimator}} + \alpha_{2j-1} u$$

$$u = e^{b_j \tau_n B} u, \quad u_{\text{Estimator}} = u_{\text{Estimator}} + \alpha_{2j} u$$

end

$$u_{n+1} = u, \quad \text{Local error estimator} = u - u_{\text{Estimator}}$$

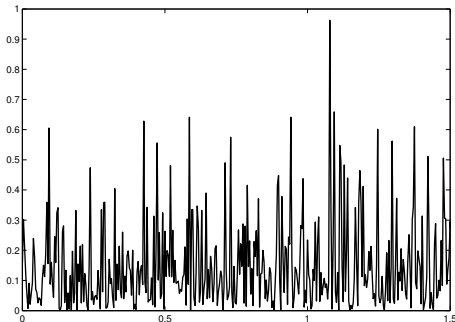
**Remark.** Extension to nonlinear evolution equations straightforward.



# Illustration (Semi-classical nonlinear Schrödinger equ.)

**Situation.** Consider nonlinear Schrödinger equation in semi-classical regime (decisive parameter  $\varepsilon > 0$ ). Time integration by fourth-order splitting method with constant time stepsize  $\Delta t = \varepsilon$  fails.

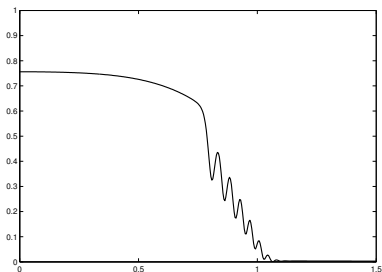
Blanes & Moan (novel,  $p = 4$ )  
Solution at time  $t = 3$ , Tolerance  $\text{tol} = 0$ , Number of time steps  $N = 300$   
Semi-classical parameter  $\text{eps} = 0.01$ ,  $M = 4096$



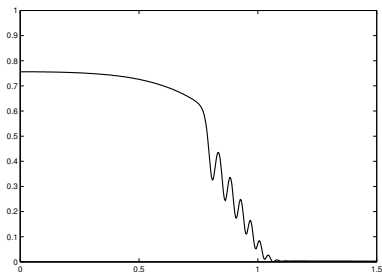
# Illustration (Semi-classical nonlinear Schrödinger equ.)

**Approach.** Use novel approach for local error control. Obtain reliable result for initial time stepsize  $\Delta t = \varepsilon$  and different tolerances.

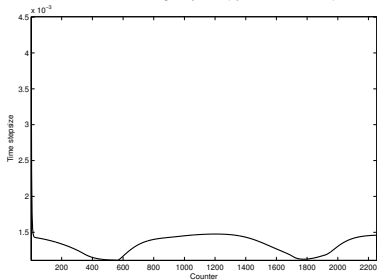
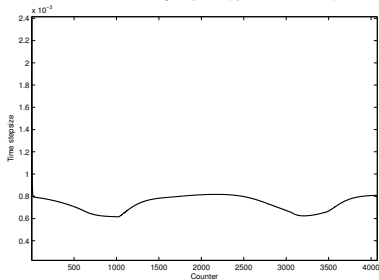
Blanes & Moan (novel,  $p = 4$ )  
Solution at time  $t = 3$ , Tolerance  $\text{tol} = 0.9$ , Number of time steps  $N = 2254$   
Semi-classical parameter  $\text{eps} = 0.01$ ,  $M = 4096$



Blanes & Moan (novel,  $p = 4$ )  
Solution at time  $t = 3$ , Tolerance  $\text{tol} = 0.5$ , Number of time steps  $N = 4073$   
Semi-classical parameter  $\text{eps} = 0.01$ ,  $M = 4096$

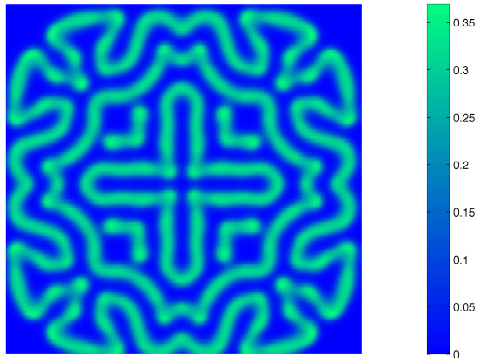


# Illustration (Semi-classical nonlinear Schrödinger equ.)

Blanes & Moan (novel,  $p = 4$ )Final time  $T = 3$ , Tolerance  $\text{tol} = 0.9$ , Total number of time steps  $N = 2254$   
Nonlinear Schrödinger equation ( $\text{eps} = 0.01$ ,  $M = 4096$ )Blanes & Moan (novel,  $p = 4$ )Final time  $T = 3$ , Tolerance  $\text{tol} = 0.5$ , Total number of time steps  $N = 4073$   
Nonlinear Schrödinger equation ( $\text{eps} = 0.01$ ,  $M = 4096$ )

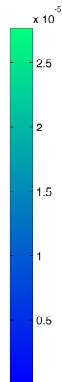
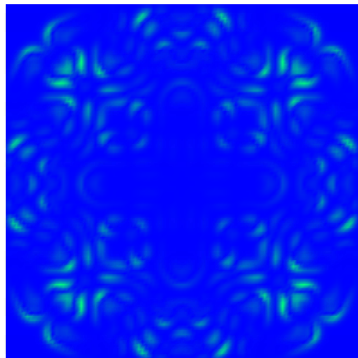
# Illustration (Gray–Scott equations)

Yoshida (complex, novel,  $p = 4$ )  
Solution at time  $t = 3000$ , Tolerance  $\text{tol} = 0.9$ , Number of time steps  $N = 2481$   
Second component,  $M = 10000$



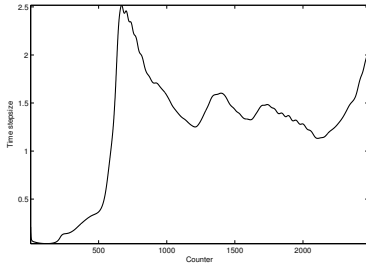
# Illustration (Gray–Scott equations)

Difference (Yoshida with tol = 0.9 and tol = 0.1)

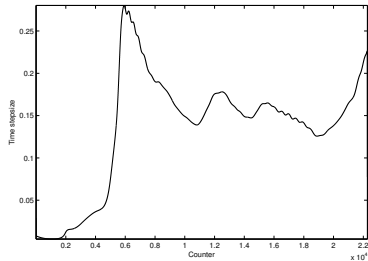


# Illustration (Gray–Scott equations)

Yoshida (complex, novel,  $p = 4$ )  
 Final time  $T = 3000$ , Tolerance  $\text{tol} = 0.9$ , Total number of time steps  $N = 2481$   
 Gray–Scott equations ( $M = 10000$ )



Yoshida (complex, novel,  $p = 4$ )  
 Final time  $T = 3000$ , Tolerance  $\text{tol} = 0.1$ , Total number of time steps  $N = 22275$   
 Gray–Scott equations ( $M = 10000$ )



# Remarks on extension to non-autonomous nonlinear evolution equations

# Extension to nonlinear evolution equations

**Approach.** Apply commutator-free quasi-Magnus integrators combined with operator splitting methods to nonlinear evolution equations of form

$$\begin{cases} u'(t) = A(t) u(t) + B(u(t)), & t \in (t_0, T), \\ u(t_0) \text{ given;} \end{cases}$$

that is, solve sequence of related autonomous nonlinear equations

$$u'(t) = \mathcal{A}_{jn} u(t) + b_j B(u(t)), \quad t \in (t_n, t_{n+1}),$$

$$\mathcal{A}_{jn} = \sum_{k=1}^K a_{jk} A(t_n + c_k \tau_n), \quad b_j = \sum_{k=1}^K a_{jk}, \quad j \in \{1, \dots, J\},$$

by means of splitting methods.



# Areas of application

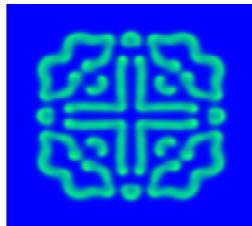
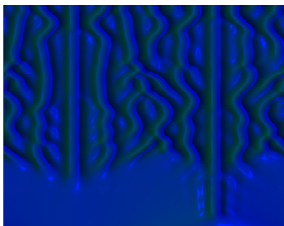
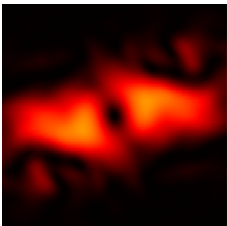
**Situation.** Consider nonlinear evolution equation of form

$$u'(t) = A(t)u(t) + B(u(t)), \quad t \in (t_0, T).$$

## Areas of application.

- ◇ Nonlinear **Schrödinger equations**  
Gross–Pitaevskii equations with opening trap  
Gross–Pitaevskii equations with rotation (moving frame)
- ◇ **Diffusion-advection-reaction systems** with multiplicative noise  
Formation of patterns in deterministic case (see illustrations)  
Gray–Scott equations with multiplicative noise (with E. HAUSENBLAS)

# Illustrations (BEC, Pattern formation)



Movies

# Conclusions and future work

# Conclusions and future work

## Summary.

- ◇ Commutator-free quasi-Magnus exponential integrators form favourable class of time discretisation methods for linear evolution equations of Schrödinger type and of parabolic type. Theoretical analysis contributes to deeper understanding (reveals approach to resolve stability issues, explains order reductions causing significant loss of accuracy).

## Current and future work.

- ◇ Study approach used for local error estimation of splitting methods.
- ◇ Study commutator-free integrators in combination with splitting methods for nonlinear equations.
  - ◇ Provide implementation for GPE (quantum turbulence).
  - ◇ Improve performance of implementation for deterministic Gray–Scott equations (GPU).

# Thank you!