

# Convergence analysis of commutator-free quasi-Magnus exponential integrators for non-autonomous linear Schrödinger equations

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# Collaborators

## My collaborators.

SERGIO BLANES, FERNANDO CASAS, CESÁREO GONZÁLEZ

## Our former work on design and error analysis of commutator-free quasi-Magnus exponential integrators applied to parabolic equations.

S. BLANES, F. CASAS, M. TH.

*Convergence analysis of high-order commutator-free quasi-Magnus exponential integrators for nonautonomous linear evolution equations of parabolic type.*  
IMA J. Numer. Anal. 38/2 (2018) 743–778.

S. BLANES, F. CASAS, M. TH.

*High-order commutator-free quasi-Magnus exponential integrators for non-autonomous linear evolution equations.*  
Comp. Phys. Commun. 220 (2017) 243–262.

## Related work on construction of local error estimators for Magnus-type integrators.

W. AUZINGER, H. HOFSTÄTTER, O. KOCH, M. QUELL, M. TH.

*A posteriori error estimation for Magnus-type integrators.*  
Submitted (2018).

# Setting CFQM exponential integrators

# Class of evolution equations

**Class of evolution equations.** Consider non-autonomous linear evolution equations of form

$$\begin{cases} u'(t) = A(t) u(t), & t \in (t_0, T), \\ u(t_0) \text{ given.} \end{cases}$$

**Applications.** Relevant applications include (large) systems of ordinary differential equations and **partial differential equations**.

- Linear evolution equations of **Schrödinger type** involving time-dependent Hamilton operators (**focus in this talk**)

$$A(t) = -iH(t).$$

- Linear evolution equations of **parabolic type** (former work).

# Illustrations

## Illustrations.

- Linear Schrödinger equations with space-time-dependent potential.  
See also work by ARIEH ISERLES, KAROLINA KROPIELNICKA, PRANAV SINGH and talk by SERGIO BLANES.
- Time-dependent Gross–Pitaevskii equations with rotation term (transformation to rotating frame, additional nonlinearity).  
See also work by WEIZHU BAO and co-authors.

[HTTP://TECHMATH.UIBK.AC.AT/MECHT/MyHOMEPAGE/RESEARCH.HTML](http://TECHMATH.UIBK.AC.AT/MECHT/MyHOMEPAGE/RESEARCH.HTML)

## Class of time integrators

**Class of time integrators.** Study **commutator-free quasi-Magnus (CFQM) exponential integrators** for efficient time integration.

- Consider time grid points and associated time stepsizes

$$t_0 < \dots < t_n < \dots < t_N = T, \quad \tau_n = t_{n+1} - t_n, \quad n \in \{0, 1, \dots, N-1\}.$$

- Choose quadrature nodes and adjust (real) method coefficients to attain certain order of consistency

$$c_k \in [0, 1], \quad a_{jk} \in \mathbb{R}, \quad (j, k) \in \{1, \dots, J\} \times \{1, \dots, K\}.$$

- Determine **numerical solution values by recurrence** of form

$$A_{nk}(\tau_n) = A(t_n + c_k \tau_n), \quad B_{nj}(\tau_n) = \sum_{k=1}^K a_{jk} A_{nk}(\tau_n),$$

$$\mathcal{S}(\tau_n, t_n) = e^{\tau_n B_{nJ}(\tau_n)} \dots e^{\tau_n B_{n1}(\tau_n)},$$

$$u_{n+1} = \mathcal{S}(\tau_n, t_n) u_n \approx u(t_{n+1}) = \mathcal{E}(\tau_n, t_n) u(t_n), \quad n \in \{0, 1, \dots, N-1\}.$$

# Which time integration methods perform best?

**Which time integration methods perform best?** Apparently not possible to provide **generally valid answer**, since performance of time integration methods substantially depends on problems under consideration and realisations of exponentials.

- Numerical examples that confirm favourable behaviour of CFQM integrators are found in literature. For **comparisons with Magnus integrators and Runge–Kutta methods** in context of parabolic and Schrödinger equations, see BLANES, CASAS, TH. (2017).
- See talks by SERGIO BLANES and PRANAV SINGH.

**Intrinsic benefit.** Intrinsic benefit of CFQM exponential integrators is that **structural properties** of defining operator family are well-preserved.

- Good stability behaviour (no stepsize restriction).
- Preservation of geometric properties.

# Main objective

**Main objective (in this talk).** Study CFQM exponential integrators in context of **linear Schrödinger equations**. Provide **rigorous theoretical convergence analysis (stability, local error)**. Note that difficulty in derivation of local error representation lies in suitable expansion of product of exponentials defining numerical solution.<sup>1</sup>

## Convergence analysis.

- For general case, adapt approach detailed in former work on parabolic equations.
- For relevant special case  $H(t) = \Delta + V(t)$ , deduce error representation that captures correctly low regularity requirements on initial state. Contrast convergence result for CFQM exponential integrators to convergence result for Magnus integrators.

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<sup>1</sup> *Be aware of presence of unbounded operators. Care about remainders. Do not use representations involving infinite series such as BCH-formula.*



# Convergence result (General case)

# Convergence result (General case)

## Theorem

Assume that the considered non-autonomous linear evolution equation is defined by a family of self-adjoint space-time-dependent operators

$$\begin{cases} u'(t) = A(t) u(t) = i H(t) u(t), & H(t) : D \rightarrow X = L_2(\Omega, \mathbb{R}), \quad t \in (t_0, T), \\ u(t_0) \text{ given.} \end{cases}$$

Suppose that the coefficients of the applied CFQM exponential integrator are real and fulfill the nonstiff  $p$ -th order conditions. Provided that compositions of the form  $A^{(\ell)}(s) u^{(m)}(t)$  with  $\ell \in \{0, 1, \dots, p\}$  and  $m \in \{0, 1, \dots, p-1\}$  remain bounded for  $s, t \in [0, T]$ , the global error estimate

$$\|u_n - u(t_n)\|_X \leq C \left( \|u_0 - u(t_0)\|_X + \tau^p \right), \quad n \in \{0, 1, \dots, N\},$$

is valid with a constant  $C > 0$  that does not depend on the number of time steps  $n$  and the (maximal) time stepsize  $\tau > 0$ .

**Implication.** For family of second-order differential operators involving regular coefficients, assumption  $A(t) u^{(p-1)}(t) \sim (A(t))^p u(t) \sim \partial_{x_1}^{2p} u(t)$  bounded in  $L_2(\Omega, \mathbb{R})$ , uniformly for  $t \in [0, T]$ , corresponds to regularity requirement  $u(t_0) \in H^{2p}(\Omega, \mathbb{R})$ .

## Convergence result (General case)

**Proof (Initial step in local error expansion).** On first sub-subinterval, employ linearisation and represent exact solution value by variation-of-constants formula

$$u'(t) = A(t) u(t) = \frac{1}{b_1} B_{n1} u(t) + \left( A(t) - \frac{1}{b_1} B_{n1} \right) u(t), \quad t \in (t_n, t_n + b_1 \tau_n),$$

$$u(t_n + b_1 \tau_n) = e^{\tau_n B_{n1}} u(t_n) + b_1 \int_0^{\tau_n} e^{(\tau_n - \sigma) B_{n1}} R_{n1}(t_n + b_1 \sigma) d\sigma.$$

Observe that remainder satisfies relation

$$R_{n1}(t) = \left( A(t) - \frac{1}{b_1} B_{n1} \right) u(t) \sim \left( A(t) - A(s) \right) u(t) \sim (t - s) A'(s) u(t),$$


$$u(t_n + b_1 \tau_n) - e^{\tau_n B_{n1}} u(t_n) = \mathcal{O}(\tau_n^2, \|A' u\|_X).$$

Proceed inductively to attain solution representation on subinterval

$$\underbrace{u(t_n + \tau_n) = u(t_n + (b_1 + \dots + b_j) \tau_n)}_{\text{exact solution value}} = \underbrace{e^{\tau_n B_{nj}(\tau_n)} \dots e^{\tau_n B_{n1}(\tau_n)} u(t_n)}_{\text{numerical solution value}} + \underbrace{\text{remainder}}_{\mathcal{O}(\tau_n^2, \|A' u\|_X)}.$$

For  $p = 1$ , this implies stated result under regularity requirement

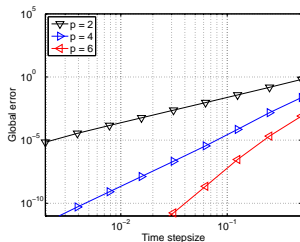
$$A^{(p)}(s) u^{(p-1)}(t) \in X, \quad s, t \in [t_0, T].$$

For  $p \geq 2$ , use similar approach for further expansion of remainder (involved calculations). 

## Convergence result (General case)

**Illustration.** Numerical examples for *characteristical test equation* confirm theoretical convergence result.

- Unconditional stability of CFQM exponential integrators.
- Full order of convergence for regular data.



# Open questions (Special case)

# Optimality of regularity requirements?

## Optimality of regularity requirements?

- Numerical verification that regularity requirements on exact solution (initial state) are optimal is difficult, since space discretisation error and errors in computation of exponentials in general dominate time discretisation error.
- Hope: In relevant special case  $H(t) = \Delta + V(t)$ , use of operator splitting methods and their realisation by Fourier spectral method permits to reduce space discretisation error and provides possibility to verify regularity requirements numerically.

## Open questions (Special case)

**Special case.** Study convergence behaviour of CFQM exponential integrators for special case

$$H(t) = \Delta + V(t).$$

### Open questions.

- What are the optimal regularity requirements on the exact solution (initial state)?  
Rigorous derivation provided for special schemes. Conjecture stated for method class.
- Does our former proof capture these regularity requirements?  
Suitable adaptation needed, since local error analysis becomes more delicate. In particular, observe that Laplacian cancels in difference  $A(t) - A(s) \sim V(t) - V(s)$ .
- Do numerical examples verify the optimal regularity requirements?  
First tests give a hint, but numerical study needs to be refined.

# Objective

**Objective.** Conjecture that for non-autonomous linear evolution equations that involve **Hamilton operators of special structure**

$$\begin{cases} u'(t) = A(t) u(t), & A(t) = i(\Delta + V(t)), \quad t \in (t_0, T), \\ u(t_0) \text{ given,} \end{cases}$$

**significantly lower regularity requirements** are sufficient to attain full order of convergence

general case:  $u(t_0) \in H^{2p}(\Omega, \mathbb{R})$ , special case:  $u(t_0) \in H^{p-1}(\Omega, \mathbb{R})$ .

Explain this observation by rigorous error analysis.

## In this talk.

- Present (briefly) basic approach.
- Contrast obtained result for CFQM exponential integrators to result for other integration methods.



# Convergence analysis (Special case)

# Basic assumption

**Basic assumption.** Consider non-autonomous linear evolution equation involving **Hamilton operator of special structure** on **first subinterval**

$$\begin{cases} u'(t) = A(t) u(t), & A(t) = i(\Delta + V(t)), \quad t \in (t_0, t_0 + \tau), \\ u(t_0) \text{ given.} \end{cases}$$

Assume that initial state and real-valued space-time-dependent potential satisfy certain regularity requirements. Employ short notation

$$\begin{aligned} \|u(t_0)\|_{H^\ell} &= \|u(t_0)\|_{H^\ell(\Omega, \mathbb{R})}, \\ \|V^{(\ell)}\|_{W_\infty^m} &= \sup_{t \in [t_0, t_0 + \tau]} \|V^{(\ell)}(t)\|_{W_\infty^m(\Omega, \mathbb{R})}. \end{aligned}$$

# Implication

**Implication.** Use unitarity of evolution operator (integration-by-parts, potential real-valued)

$$\frac{d}{dt} \|u(t)\|_{L_2}^2 = 2 \Re \left( u(t) \middle| u'(t) \right)_{L_2} = 2 \Re \left( i \|\nabla u(t)\|_{L_2}^2 - i \left( V(t) \middle| |u(t)|^2 \right)_{L_2} \right) = 0,$$
$$\|u(t)\|_{L_2} = \|u(t_0)\|_{L_2}, \quad t \in [t_0, t_0 + \tau],$$

and representation by variation-of-constants formula to justify that **exact solution inherits regularity of initial state**, e.g.

$$\chi(t) = \partial_x u(t), \quad \chi'(t) = i(\Delta + V(t))\chi(t) + i\partial_x V(t)u(t),$$
$$\|u(t)\|_{H^1} \leq \left(1 + \tau \|V\|_{W_\infty^1}\right) \|u(t_0)\|_{H^1}.$$

# Integrators

**CFQM exponential integrators.** Study lower- and higher-order CFQM exponential integrators (first time step).

- Apply **second-order exponential midpoint rule** based on single Gaussian quadrature node and single exponential

$$p = 2, \quad J = 1 = K, \quad \mathcal{S}(\tau) u(t_0) = e^{\tau A(t_0 + \frac{1}{2}\tau)} u(t_0) \approx u(t_0 + \tau).$$

- Apply **fourth-order CFQM exponential integrator** based on two Gaussian quadrature nodes and two exponentials

$$p = 4, \quad J = 2 = K, \quad \alpha = \frac{\sqrt{3}}{6}, \quad c_1 = \frac{1}{2} - \alpha, \quad c_2 = \frac{1}{2} + \alpha,$$

$$a_{11} = \frac{1}{4} + \alpha = a_{22}, \quad a_{12} = \frac{1}{4} - \alpha = a_{21},$$

$$b_1 = a_{11} + a_{12} = b_2 = a_{21} + a_{22} = \frac{1}{2},$$

$$B_j(\tau) = a_{j1} A(t_0 + c_1\tau) + a_{j2} A(t_0 + c_2\tau), \quad j \in \{1, 2\},$$

$$\mathcal{S}(\tau) u(t_0) = e^{\tau B_2(\tau)} e^{\tau B_1(\tau)} u(t_0) \approx u(t_0 + \tau).$$

Note that symmetry suggests linearisation about midpoint  $A_* = A(t_0 + \frac{\tau}{2})$ .



# Stability

**Stability.** Assume that **method coefficients** are **real**

$$a_{jk} \in \mathbb{R}, \quad (j, k) \in \{1, \dots, J\} \times \{1, \dots, K\}.$$

As operators defining CFQM exponential integrators rewrite as follows

$$B_j(\tau) = \sum_{k=1}^K a_{jk} A(t_0 + c_k \tau),$$

$$A(t) = i(\Delta + V(t)), \quad b_j = \sum_{k=1}^K a_{jk},$$

$$B_j(\tau) = i \left( b_j \Delta + \sum_{k=1}^K a_{jk} V(t_0 + c_k \tau) \right),$$

**stability in  $L_2(\Omega, \mathbb{R})$**  is ensured by **unitarity** of arising evolution operators

$$\left\| e^{tB_j(\tau)} \dots e^{tB_1(\tau)} u(t_0) \right\|_{L_2} = \|u(t_0)\|_{L_2}, \quad t \in [0, \tau].$$

# Approach

## Approach.

- Deduce **local error expansion** that remains appropriate for **unbounded Hamilton operators**, reflects **correct order** with respect to time stepsize, and captures observed **regularity requirements** on exact solution

$$\mathcal{S}(\tau) u(t_0) - u(t_0 + \tau) = \mathcal{O}\left(\tau^{p+1}, \|V^{(\ell)}\|_{W_\infty^m}, \|u\|_{H^{p-1}}\right).$$

- Consider evolution equations satisfied by exact solution and by exponentials defining numerical solution.
- Employ linearisations about midpoint and representations by variation-of- constants formula.
- Observe that in expansions of integrands iterated commutators implying certain regularity requirements arise naturally.
- Together with stability bound, obtain **global error bound** of form

$$\|u_n - u(t_n)\|_{L_2} \leq C\left(\|V^{(\ell)}\|_{W_\infty^m}\right) t_n \tau^p \|u\|_{H^{p-1}}.$$

# Conjecture

## Theorem

Assume that the considered non-autonomous linear evolution equation is defined by a family of self-adjoint space-time-dependent operators

$$\begin{cases} u'(t) = A(t) u(t) = i H(t) u(t), & H(t) : D \rightarrow X = L_2(\Omega, \mathbb{R}), \quad t \in (t_0, T), \\ u(t_0) \text{ given,} \end{cases}$$

Then, any  $p$ -th order CFQM exponential integrator with real coefficients satisfies the global error estimate

$$\|u_n - u(t_n)\|_{L_2} \leq C \left( \|u_0 - u(t_0)\|_{L_2} + \tau^p \right), \quad n \in \{0, 1, \dots, N\},$$

with a constant that depends on  $\|V^{(\ell)}\|_{W_\infty^m}$  and  $\|u\|_{H^{p-1}}$  but is independent of the number of time steps  $n$  and the (maximal) time stepsize  $\tau > 0$ .

**Proof.** Rigorous derivation completed for  $p = 4$  and  $J = K = 2$ .



# Comparison

**Comparison with classical methods.** Note that boundedness of higher time derivatives of solution corresponds to spatial regularity, since

$$u'(t) = A(t) u(t), \quad u''(t) = A'(t) u(t) + A(t) u'(t) \sim (A(t))^2 u(t), \\ u'''(t) \sim (A(t))^3 u(t), \quad \|u'''\|_{L_2} \sim \|u\|_{H^6}.$$

Convergence result for CFQM exponential integrators confirms superior behaviour compared to classical methods, e.g. of exponential midpoint rule versus implicit midpoint rule

$$\|u_n - u(t_n)\|_{L_2} \leq C t_n \tau^2 \|u'''\|_{L_2}.$$



# Comparison

**Comparison with Magnus integrators.** Conjectured convergence result for CFQM exponential integrators compares with work on (interpolatory) **Magnus integrators** (in context of spatial semi-discretisation).

- CFQM exponential integrators: **Same regularity requirement on exact solution. Time stepsize restriction not needed.**

**Theorem (HOCHBRUCK, LUBICH, 2003)**

Consider  $A(t) = i(U + V(t))$  with symmetric positive-definite matrix  $U$  and Hermitian matrix-valued function  $V$ . Assume that the time-derivatives of  $V$  are uniformly bounded and that the commutator bounds  $(m \in \{0, 1, \dots, p\}, k \in \{1, \dots, (p-1)p-1\})$

$$\|V^{(m)}(t)\| \leq M_p, \quad \|[A(t_k), \dots, [A(t_1), V^{(m)}(t)] \dots] w\| \leq K \|D^k w\|, \quad D = U^{\frac{1}{2}},$$

hold. Under the **stepsize restriction**  $\tau \|D\| \leq c$ , the  $p$ -th order Magnus integrator satisfies the error bound

$$\|u_n - u(t_n)\| \leq C(p, c, M_p, K) t_n \tau^p \sup_{t \in [0, t_n]} \|D^{p-1} u(t)\|.$$

# Conclusions

**Conclusions.** Convergence analysis provided for CFQM exponential integrators applied to non-autonomous linear Schrödinger equations.

**Open questions.** Proceed with study of special case  $H(t) = \Delta + V(t)$ .

- Extend rigorous derivation to other higher-order methods.
- Confirm optimality of regularity requirements by numerical examples.

**Thank you!**

# Proof

## Local error expansion

# Linearisations

**Linearisations.** Consider evolution equations for numerical and exact solutions, and employ linearisations about midpoint of first subinterval.

- Employ abbreviations

$$A(t) = i(\Delta + V(t)), \quad A_* = A(t_0 + \frac{\tau}{2}), \quad V_* = V(t_0 + \frac{\tau}{2}),$$

$$R(t) = A(t) - A_* = i(V(t) - V_*) = \mathcal{O}\left(\tau, \|V'\|_{L_\infty}\right).$$

- Observe that numerical solution is composed by exponentials and that associated evolution equations rewrite as follows

$$\mathcal{S}(\tau) u(t_0) = e^{\tau B_2(\tau)} e^{\tau B_1(\tau)} u(t_0),$$

$$w_j(t) = e^{t B_j(\tau)}, \quad B_j(\tau) = a_{j1} A(t_0 + c_1 \tau) + a_{j2} A(t_0 + c_2 \tau), \quad b_j = a_{j1} + a_{j2} = \frac{1}{2},$$

$$S_j(\tau) = \frac{1}{b_j} (B_j(\tau) - b_j A_*) = 2(a_{j1} R(t_0 + c_1 \tau) + a_{j2} R(t_0 + c_2 \tau)) = \mathcal{O}\left(\tau, \|V'\|_{L_\infty}\right),$$

$$w'_j(t) = B_j(\tau) w_j(t) = b_j A_* w_j(t) + b_j S_j(\tau) w_j(t) = \frac{1}{2} A_* w_j(t) + \frac{1}{2} S_j(\tau) w_j(t), \quad t \in (0, \tau).$$

- Rewrite evolution equation in analogous manner

$$u'(t) = A(t) u(t) = A_* u(t) + R(t) u(t), \quad t \in (t_0, t_0 + \tau),$$

$$u(t_0 + \tau) = \mathcal{E}(\tau) u(t_0) = \mathcal{E}\left(\frac{\tau}{2}\right) \mathcal{E}\left(\frac{\tau}{2}\right) u(t_0).$$

# Auxiliary evolution equation

**Auxiliary evolution equation.** Above relations suggest consideration of linear evolution equation of form (neglect values of arising constants)

$$y'(t) = Z_* y(t) + z(t) y(t), \quad t \in (s, s + \tau),$$

Numerical solution:  $Z_* = \alpha A_*, \quad z(t) = \alpha S_j(\tau) = \mathcal{O}\left(\tau, \|V'\|_{L_\infty}\right),$

Exact solution  $Z_* = \alpha A_*, \quad z(t) = \alpha R(t) = \mathcal{O}\left(\tau, \|V'\|_{L_\infty}\right).$

# Main tool

**Main tool.** Consider linear evolution equation of form

$$y'(t) = Z_* y(t) + z(t) y(t), \quad t \in (s, s + \tau).$$

Employ representations of solution values by variation-of-constants formula

$$y(s+t) = e^{tZ_*} y(s) + \int_0^t e^{(t-\sigma_1)Z_*} z(s+\sigma_1) y(s+\sigma_1) d\sigma_1, \quad t \in (0, \tau),$$

$$y(s+\sigma_1) = e^{\sigma_1 Z_*} y(s) + \int_0^{\sigma_1} e^{(\sigma_1-\sigma_2)Z_*} z(s+\sigma_2) y(s+\sigma_2) d\sigma_2.$$

In view of further expansion for higher-order scheme, rewrite resulting identity as

$$\begin{aligned} y(s+t) &= e^{tZ_*} \left( I + \int_0^t \underbrace{e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*}}_{= Z(s, \sigma_1)} d\sigma_1 \right) y(s) \\ &+ e^{tZ_*} \int_0^t \int_0^{\sigma_1} \underbrace{e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*}}_{= Z(s, \sigma_1)} \underbrace{e^{-\sigma_2 Z_*} z(s+\sigma_2)}_{= Z(s, \sigma_2) e^{-\sigma_2 Z_*}} y(s+\sigma_2) d\sigma_2 d\sigma_1. \end{aligned}$$

# Representations

**Representations.** Use as well alternative representation obtained by linear transformation  
 $(\sigma_1, \sigma_2) \leftrightarrow (t - \sigma_1, t - \sigma_2)$

$$\begin{aligned}
 y(s+t) &= e^{tZ_*} \left( I + \int_0^t \underbrace{e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*}}_{= Z(s, \sigma_1)} d\sigma_1 \right) y(s) \\
 &\quad + e^{tZ_*} \int_0^t \int_0^{\sigma_1} \underbrace{e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*}}_{= Z(s, \sigma_1)} \underbrace{e^{-\sigma_2 Z_*} z(s+\sigma_2)}_{= Z(s, \sigma_2) e^{-\sigma_2 Z_*}} y(s+\sigma_2) d\sigma_2 d\sigma_1 \\
 &= \left( I + \int_0^t \underbrace{e^{\sigma_1 Z_*} z(s+t-\sigma_1) e^{-\sigma_1 Z_*}}_{= Z(s+t, -\sigma_1)} d\sigma_1 \right) e^{tZ_*} y(s) \\
 &\quad + \int_0^t \int_{t-\sigma_1}^t \underbrace{e^{\sigma_1 Z_*} z(s+t-\sigma_1) e^{-\sigma_1 Z_*}}_{= Z(s+t, -\sigma_1)} \underbrace{e^{\sigma_2 Z_*} z(s+t-\sigma_2)}_{= Z(s+t, -\sigma_2) e^{(\sigma_2-t)Z_*}} y(s+t-\sigma_2) d\sigma_2 d\sigma_1.
 \end{aligned}$$

**Remark.** Recall former relation and unitarity of evolution operator

$$z(s+\sigma) = \mathcal{O}(\tau, \|V'\|_{L_\infty}), \quad Z(s, \sigma) = e^{-\sigma Z_*} z(s+\sigma) e^{\sigma Z_*} = \mathcal{O}(\tau, \|V'\|_{L_\infty}), \quad \sigma \in [0, \tau].$$

# First expansion ( $p = 2$ )

**First expansion.** In context of 2nd-order method, employ expansion

$$\begin{aligned}
 y(s+t) &= e^{tZ_*} \left( I + \int_0^t \underbrace{e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*}}_{= Z(s, \sigma_1)} d\sigma_1 \right) y(s) \\
 &+ e^{tZ_*} \int_0^t \int_0^{\sigma_1} \underbrace{e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*}}_{= Z(s, \sigma_1)} \underbrace{e^{-\sigma_2 Z_*} z(s+\sigma_2)}_{= Z(s, \sigma_2) e^{-\sigma_2 Z_*}} y(s+\sigma_2) d\sigma_2 d\sigma_1. \\
 &\underbrace{\hspace{15em}}_{= \mathcal{O}(\tau^4, \|V'\|_{L_\infty}, \|y\|_{L_2})}
 \end{aligned}$$



## First expansion ( $p = 4$ )

**First expansion.** In context of 4th-order method, perform additional expansion step and employ equivalent representations

$$\begin{aligned}
 & y(s+t) \\
 &= e^{tZ_*} \left( I + \underbrace{\int_0^t e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*} d\sigma_1}_{= Z(s, \sigma_1)} + \int_0^t \int_0^{\sigma_1} Z(s, \sigma_1) Z(s, \sigma_2) d\sigma_2 d\sigma_1 \right) y(s) \\
 &\quad + \underbrace{e^{tZ_*} \int_0^t \int_0^{\sigma_1} \int_0^{\sigma_2} Z(s, \sigma_1) Z(s, \sigma_2) Z(s, \sigma_3) e^{-\sigma_3 Z_*} y(s+\sigma_3) d\sigma_3 d\sigma_2 d\sigma_1}_{= \mathcal{O}(\tau^6, \|V'\|_{L_\infty}, \|y\|_{L_2})} \\
 &= \left( I + \int_0^t Z(s+t, -\sigma_1) d\sigma_1 + \int_0^t \int_{t-\sigma_1}^t Z(s+t, -\sigma_1) Z(s+t, -\sigma_2) d\sigma_2 d\sigma_1 \right) e^{tZ_*} y(s) \\
 &\quad + \underbrace{\int_0^t \int_{t-\sigma_1}^t \int_{t-\sigma_2}^t Z(s+t, -\sigma_1) Z(s+t, -\sigma_2) Z(s+t, -\sigma_3) e^{tZ_*} e^{(\sigma_3-t)Z_*} y(s+t-\sigma_3) d\sigma_3 d\sigma_2 d\sigma_1}_{= \mathcal{O}(\tau^6, \|V'\|_{L_\infty}, \|y\|_{L_2})}.
 \end{aligned}$$

# Taylor series expansion

**Taylor series expansion.** Note that iterated commutators arise naturally

$$\begin{aligned} f(\sigma) &= e^{-\sigma Z_*} F e^{\sigma Z_*}, \\ f'(\sigma) &= e^{-\sigma Z_*} (-Z_* F + F Z_*) e^{\sigma Z_*} = e^{-\sigma Z_*} [F, Z_*] e^{\sigma Z_*} = e^{-\sigma Z_*} \operatorname{ad}_{Z_*}(F) e^{\sigma Z_*}, \\ f''(\sigma) &= e^{-\sigma Z_*} [[F, Z_*], Z_*] e^{\sigma Z_*} = e^{-\sigma Z_*} \operatorname{ad}_{Z_*}^2(F) e^{\sigma Z_*}, \\ f'''(\sigma) &= e^{-\sigma Z_*} \operatorname{ad}_{Z_*}^3(F) e^{\sigma Z_*}. \end{aligned}$$

Stepwise Taylor series expansion yields relations

$$\begin{aligned} f(\sigma) - f(\sigma_0) &= f(\theta\sigma + (1-\theta)\sigma_0) \Big|_{\theta=0}^1 \\ &= (\sigma - \sigma_0) \int_0^1 f'(\theta\sigma + (1-\theta)\sigma_0) d\theta, \\ &= (\sigma - \sigma_0) f'(\sigma_0) \\ &\quad + (\sigma - \sigma_0)^2 \int_0^1 (1-\theta) f''(\theta\sigma + (1-\theta)\sigma_0) d\theta, \\ &= (\sigma - \sigma_0) f'(\sigma_0) + \frac{1}{2} (\sigma - \sigma_0)^2 f''(\sigma_0) \\ &\quad + \frac{1}{2} (\sigma - \sigma_0)^3 \int_0^1 (1-\theta)^2 f'''(\theta\sigma + (1-\theta)\sigma_0) d\theta. \end{aligned}$$

# Commutators

**Commutators.** Recall that in present situation

$$Z_* \sim A_* \sim \Delta + V(t_0 + \frac{\tau}{2}), \quad F \sim z(t) \sim \begin{cases} R(t), \\ S_j(\tau), \end{cases}$$

$$F \sim V(t) - V(s), \quad s, t \in [t_0, t_0 + \tau], \quad Fw = \mathcal{O}(\|V\|_{L_\infty}, \|w\|_{L_2}) = \mathcal{O}(\tau, \|V'\|_{L_\infty}, \|w\|_{L_2}).$$

Determine iterated commutators

$$W \sim V(t) - V(s),$$

$$[W, \partial_{xx}]w \sim \partial_x W \partial_x w + \partial_{xx} W w,$$

$$\|[W, A_*]w\|_{L_2} = \mathcal{O}(\|V\|_{W_\infty^2}, \|w\|_{H^1}) = \mathcal{O}(\tau, \|V'\|_{W_\infty^2}, \|w\|_{H^1}),$$

$$\|[[W, A_*], A_*]w\|_{L_2} = \mathcal{O}(\|V\|_{W_\infty^4}, \|w\|_{H^2}) = \mathcal{O}(\tau, \|V'\|_{W_\infty^4}, \|w\|_{H^2}),$$

$$\|\text{ad}_{A_*}^k(W)w\|_{L_2} = \mathcal{O}(\|V\|_{W_\infty^{2k}}, \|w\|_{H^k}) = \mathcal{O}(\tau, \|V'\|_{W_\infty^{2k}}, \|w\|_{H^k}).$$

## Second expansion

**Taylor series expansion.** Obtain relations

$$\begin{aligned}
 e^{-\sigma Z_*} F e^{\sigma Z_*} w &= e^{-\sigma_0 Z_*} F e^{\sigma_0 Z_*} w \\
 &+ \underbrace{(\sigma - \sigma_0) \int_0^1 e^{-(\theta\sigma + (1-\theta)\sigma_0)Z_*} [F, Z_*] e^{(\theta\sigma + (1-\theta)\sigma_0)Z_*} w \, d\theta}_{= \mathcal{O}\left(\tau, \|V\|_{W_\infty^2}, \|w\|_{H^1}\right) = \mathcal{O}\left(\tau^2, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right)} \\
 e^{-\sigma Z_*} F e^{\sigma Z_*} w &= e^{-\sigma_0 Z_*} \left( F + (\sigma - \sigma_0) [F, Z_*] + \frac{1}{2} (\sigma - \sigma_0)^2 [[F, Z_*], Z_*] \right) e^{\sigma_0 Z_*} w \\
 &+ \underbrace{\frac{1}{2} (\sigma - \sigma_0)^3 \int_0^1 (1-\theta)^2 e^{-(\theta\sigma + (1-\theta)\sigma_0)Z_*} \text{ad}_{Z_*}^3(F) e^{(\theta\sigma + (1-\theta)\sigma_0)Z_*} w \, d\theta}_{= \mathcal{O}\left(\tau^3, \|V\|_{W_\infty^6}, \|w\|_{H^3}\right) = \mathcal{O}\left(\tau^4, \|V'\|_{W_\infty^6}, \|w\|_{H^3}\right)}.
 \end{aligned}$$

# Exponential midpoint rule

# Summary

**Summary** ( $p = 2$ ). Linearisation about midpoint of first subinterval, iterated application of variation-of-constants formula, and Taylor series expansion of integrand yields

$$\begin{aligned}
 y(s+t) &= e^{tZ_*} y(s) \\
 &+ e^{(t-\sigma_0)Z_*} \int_0^t z(s+\sigma_1) d\sigma_1 e^{\sigma_0 Z_*} y(s) \\
 &+ \underbrace{\int_0^t \int_0^1 (\sigma_1 - \sigma_0) e^{(t-\theta\sigma_1 - (1-\theta)\sigma_0)Z_*} [z(s+\sigma_1), Z_*] e^{(\theta\sigma_1 + (1-\theta)\sigma_0)Z_*} y(s) d\theta d\sigma_1}_{= \mathcal{O}(\tau^3, \|V'\|_{W_\infty^2}, \|y\|_{H^1})} \\
 &+ \underbrace{e^{tZ_*} \int_0^t \int_0^{\sigma_1} Z(s, \sigma_1) Z(s, \sigma_2) e^{-\sigma_2 Z_*} y(s+\sigma_2) d\sigma_2 d\sigma_1}_{= \mathcal{O}(\tau^4, \|V'\|_{L_\infty}, \|y\|_{L_2})} \\
 &= e^{tZ_*} y(s) \\
 &+ e^{(t-\sigma_0)Z_*} \int_0^t z(s+\sigma_1) d\sigma_1 e^{\sigma_0 Z_*} y(s) \\
 &+ \mathcal{O}(\tau^3, \|V'\|_{W_\infty^2}, \|y\|_{H^1}).
 \end{aligned}$$

## Local error expansion (Exponential midpoint rule)

**Specification.** Specification of above relation to exponential midpoint rule leads to relation ( $y = u$ ,  $s = t_0$ ,  $t = \tau$ ,  $Z_* = A_* = A(t_0 + \frac{\tau}{2})$ ,  $z = R$ ,  $\sigma_0 = 0$ )

$$u(t_0 + \tau) = e^{\tau A_*} u(t_0) + e^{\tau A_*} \int_0^\tau R(t_0 + \sigma_1) d\sigma_1 u(t_0) + \mathcal{O}\left(\tau^3, \|V'\|_{W_\infty^2}, \|u\|_{H^1}\right).$$

Evidently this implies local error expansion

$$\begin{aligned} u(t_0 + \tau) - \mathcal{S}(\tau) u(t_0) &= u(t_0 + \tau) - e^{\tau A_*} u(t_0) \\ &= e^{\tau A_*} \int_0^\tau \underbrace{R(t_0 + \sigma_1)}_{=i\left(V(t) - V\left(t_0 + \frac{\tau}{2}\right)\right)} d\sigma_1 u(t_0) + \mathcal{O}\left(\tau^3, \|V'\|_{W_\infty^2}, \|u\|_{H^1}\right). \end{aligned}$$

In final step, use that  $R(t_0 + \frac{\tau}{2}) = 0$ ,  $R'(t) = iV'(t)$ ,  $R''(t) = iV''(t)$  and hence by Taylor series expansion about midpoint

$$\begin{aligned} R(t_0 + \sigma_1) &= \left(\sigma_1 - \frac{\tau}{2}\right) iV'\left(t_0 + \frac{\tau}{2}\right) + \left(\sigma_1 - \frac{\tau}{2}\right)^2 \int_0^1 (1-\theta) iV''\left(t_0 + \theta\sigma_1 + (1-\theta)\frac{\tau}{2}\right) d\theta, \\ e^{\tau A_*} \int_0^\tau R(t_0 + \sigma_1) d\sigma_1 u(t_0) &= i e^{\tau A_*} \underbrace{\int_0^\tau \left(\sigma_1 - \frac{\tau}{2}\right) d\sigma_1}_{=0} V'\left(t_0 + \frac{\tau}{2}\right) u(t_0) + \mathcal{O}\left(\tau^3, \|V''\|_{L_\infty}, \|u\|_{H^1}\right). \end{aligned}$$

# Local error expansion (Exponential midpoint rule)

**Local error expansion.** Altogether, attain local error expansion for exponential midpoint rule that reflects expected dependencies

$$u(t_0 + \tau) - e^{\tau A^*} u(t_0) = \mathcal{O}\left(\tau^3, \|V'\|_{W_\infty^2}, \|V''\|_{L_\infty}, \|u\|_{H^1}\right).$$

## Theorem

Assume that the considered non-autonomous linear evolution equation is defined by a family of self-adjoint space-time-dependent operators

$$\begin{cases} u'(t) = A(t) u(t) = i H(t) u(t), & H(t) : D \rightarrow X = L_2(\Omega, \mathbb{R}), \quad t \in (t_0, T), \\ u(t_0) \text{ given,} \end{cases}$$

Then, the exponential midpoint rule satisfies the global error estimate

$$\|u_n - u(t_n)\|_{L_2} \leq C \left( \|u_0 - u(t_0)\|_{L_2} + \tau^2 \right), \quad n \in \{0, 1, \dots, N\},$$

with a constant  $C > 0$  that depends on  $\|V'\|_{W_\infty^2}$ ,  $\|V''\|_{L_\infty}$  and  $\|u\|_{H^1}$  but is independent of the number of time steps  $n$  and the (maximal) time stepsize  $\tau > 0$ .



# Fourth-order method

# Summary

**Summary.** In context of 4th-order method, employ expansion

$$y(s+t) = e^{tZ_*} \left( I + \mathcal{J}_2(s, t, Z_*, z) + \mathcal{J}_4(s, t, Z_*, z) \right) y(s) + \mathcal{O} \left( \tau^6, \|V'\|_{L_\infty}, \|y\|_{L_2} \right),$$

$$\mathcal{J}_2(s, t, Z_*, z) = \int_0^t e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*} d\sigma_1,$$

$$\mathcal{J}_4(s, t, Z_*, z) = \int_0^t \int_0^{\sigma_1} e^{-\sigma_1 Z_*} z(s+\sigma_1) e^{\sigma_1 Z_*} e^{-\sigma_2 Z_*} z(s+\sigma_2) e^{\sigma_2 Z_*} d\sigma_2 d\sigma_1,$$

as well as alternative representation (for first integral, use transformation  $\sigma \leftrightarrow -\sigma$ )

$$y(s+t) = \left( I + \mathcal{K}_2(s, t, Z_*, z) + \mathcal{K}_4(s, t, Z_*, z) \right) e^{tZ_*} y(s) + \mathcal{O} \left( \tau^6, \|V'\|_{L_\infty}, \|y\|_{L_2} \right),$$

$$\mathcal{K}_2(s, t, Z_*, z) = \int_0^t e^{\sigma_1 Z_*} z(s+t-\sigma_1) e^{-\sigma_1 Z_*} d\sigma_1 = \int_{-t}^0 e^{-\sigma_1 Z_*} z(s+t+\sigma_1) e^{\sigma_1 Z_*} d\sigma_1,$$

$$\mathcal{K}_4(s, t, Z_*, z) = \int_0^t \int_{t-\sigma_1}^t e^{\sigma_1 Z_*} z(s+t-\sigma_1) e^{-\sigma_1 Z_*} e^{\sigma_2 Z_*} z(s+t-\sigma_2) e^{-\sigma_2 Z_*} d\sigma_2 d\sigma_1.$$

Note that for time-independent  $z = S$

$$\mathcal{J}_2(\cdot, t, \frac{1}{2} Z_*, \frac{1}{2} S) = \mathcal{J}_2(\cdot, \frac{t}{2}, Z_*, S), \quad \mathcal{K}_2(\cdot, t, \frac{1}{2} Z_*, \frac{1}{2} S) = \mathcal{K}_2(\cdot, \frac{t}{2}, Z_*, S),$$

$$\mathcal{J}_4(\cdot, t, \frac{1}{2} Z_*, \frac{1}{2} S) = \mathcal{J}_4(\cdot, \frac{t}{2}, Z_*, S), \quad \mathcal{K}_4(\cdot, t, \frac{1}{2} Z_*, \frac{1}{2} S) = \mathcal{K}_4(\cdot, \frac{t}{2}, Z_*, S).$$

# Application

**Application.** Recall abbreviations

$$\begin{aligned}
 A(t) &= i(\Delta + V(t)), \quad A_* = A(t_0 + \frac{\tau}{2}), \quad V_* = V(t_0 + \frac{\tau}{2}), \\
 R(t) &= i(V(t) - V_*) = \mathcal{O}(\tau, \|V'\|_{L_\infty}), \\
 S_j(\tau) &= 2(a_{j1} R(t_0 + c_1 \tau) + a_{j2} R(t_0 + c_2 \tau)) = \mathcal{O}(\tau, \|V'\|_{L_\infty}).
 \end{aligned}$$

Recall relations for numerical and exact solutions

$$\begin{aligned}
 w'_j(t) &= \frac{1}{2} A_* w_j(t) + \frac{1}{2} S_j(\tau) w_j(t), \quad Z_* = \frac{1}{2} A_*, \quad z = \frac{1}{2} S_j(\tau), \\
 \mathcal{S}(\tau) u(t_0) &= w_2(\tau) w_1(\tau) u(t_0), \\
 u'(t) &= A_* u(t) + R(t) u(t), \quad Z_* = A_*, \quad z = R, \\
 u(t_0 + \tau) &= \mathcal{E}(\frac{\tau}{2}) \mathcal{E}(\frac{\tau}{2}) u(t_0).
 \end{aligned}$$

# Application

**Application.** Attain relation for numerical solution value

$$\begin{aligned}
 \mathcal{S}(\tau) u(t_0) &= e^{\frac{\tau}{2} A^*} \left( I + \mathcal{J}_2\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) + \mathcal{J}_4\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) \right) \\
 &\quad \times \left( I + \mathcal{K}_2\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) + \mathcal{K}_4\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) \right) e^{\frac{\tau}{2} A^*} u(t_0) \\
 &\quad + \mathcal{O}\left(\tau^6, \|V'\|_{L_\infty}, \|u\|_{L_2}\right) \\
 &= e^{\frac{\tau}{2} A^*} \left( I + \mathcal{J}_2\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) + \mathcal{K}_2\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) \right. \\
 &\quad + \mathcal{J}_2\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) \mathcal{K}_2\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) \\
 &\quad \left. + \mathcal{J}_4\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) + \mathcal{K}_4\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) \right) e^{\frac{\tau}{2} A^*} u(t_0) \\
 &\quad + \mathcal{O}\left(\tau^6, \|V'\|_{L_\infty}, \|u\|_{L_2}\right).
 \end{aligned}$$

# Application

**Application.** Attain relation for exact solution value

$$\begin{aligned}
 u(t_0 + \tau) &= e^{\frac{\tau}{2}A_*} \left( I + \mathcal{I}_2\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right) + \mathcal{I}_4\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right) \right) \\
 &\quad \times \left( I + \mathcal{K}_2\left(t_0, \frac{\tau}{2}, A_*, R\right) + \mathcal{K}_4\left(t_0, \frac{\tau}{2}, A_*, R\right) \right) e^{\frac{\tau}{2}A_*} u(t_0) \\
 &\quad + \mathcal{O}\left(\tau^6, \|V'\|_{L_\infty}, \|u\|_{L_2}\right), \\
 &= e^{\frac{\tau}{2}A_*} \left( I + \mathcal{I}_2\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right) + \mathcal{K}_2\left(t_0, \frac{\tau}{2}, A_*, R\right) \right. \\
 &\quad \left. + \mathcal{I}_2\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right) \mathcal{K}_2\left(t_0, \frac{\tau}{2}, A_*, R\right) \right. \\
 &\quad \left. + \mathcal{I}_4\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right) + \mathcal{K}_4\left(t_0, \frac{\tau}{2}, A_*, R\right) \right) e^{\frac{\tau}{2}A_*} u(t_0) \\
 &\quad + \mathcal{O}\left(\tau^6, \|V'\|_{L_\infty}, \|u\|_{L_2}\right).
 \end{aligned}$$

# Local error (Integral representation)

**Local error.** Attain relation for local error

$$\begin{aligned}
 \mathcal{S}(\tau) u(t_0) - u(t_0 + \tau) &= e^{\frac{\tau}{2} A_*} \left( \mathcal{I}_2(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)) - \mathcal{I}_2(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) \right. \\
 &\quad + \mathcal{K}_2(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)) - \mathcal{K}_2(t_0, \frac{\tau}{2}, A_*, R) \\
 &\quad + \mathcal{I}_2(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)) \mathcal{K}_2(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)) \\
 &\quad - \mathcal{I}_2(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) \mathcal{K}_2(t_0, \frac{\tau}{2}, A_*, R) \\
 &\quad + \mathcal{I}_4(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)) - \mathcal{I}_4(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) \\
 &\quad \left. + \mathcal{K}_4(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)) - \mathcal{K}_4(t_0, \frac{\tau}{2}, A_*, R) \right) e^{\frac{\tau}{2} A_*} u(t_0) \\
 &+ \mathcal{O}\left(\tau^6, \|V'\|_{L_\infty}, \|u\|_{L_2}\right).
 \end{aligned}$$

# Local error (Integral representation)

**Local error.** Rewrite local error expansion as follows

$$\begin{aligned} \mathcal{S}(\tau) u(t_0) - u(t_0 + \tau) &= e^{\frac{\tau}{2} A_*} (D_{21}(\tau) + D_{22}(\tau) + D_{41}(\tau) + D_{42}(\tau) + D_{43}(\tau)) e^{\frac{\tau}{2} A_*} u(t_0) \\ &\quad + \mathcal{O}\left(\tau^6, \|V'\|_{L_\infty}, \|u\|_{L_2}\right), \end{aligned}$$

and distinguish terms of different (a priori) orders

$$\begin{aligned} D_{21}(\tau) &= \mathcal{J}_2\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) - \mathcal{J}_2\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right), \\ D_{22}(\tau) &= \mathcal{K}_2\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) - \mathcal{K}_2\left(t_0, \frac{\tau}{2}, A_*, R\right), \\ D_{41}(\tau) &= \mathcal{J}_4\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) - \mathcal{J}_4\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right), \\ D_{42}(\tau) &= \mathcal{K}_4\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) - \mathcal{K}_4\left(t_0, \frac{\tau}{2}, A_*, R\right), \\ D_{43}(\tau) &= \mathcal{J}_2\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) \mathcal{K}_2\left(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)\right) - \mathcal{J}_2\left(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R\right) \mathcal{K}_2\left(t_0, \frac{\tau}{2}, A_*, R\right), \\ D_{41}(\tau) &= D_{42}(\tau) = D_{43}(\tau) = \mathcal{O}\left(\tau^4\right). \end{aligned}$$

## Local error (Taylor series expansion)

**Taylor series expansion.** First, employ Taylor series expansion (certain simplification in computation of arising integrals for choice  $\sigma_0 = 0$ , seems that there is no reason for alternative choice)

$$\begin{aligned} e^{-\sigma A_*} F e^{\sigma A_*} w &= F w + \mathcal{O}\left(\tau^2, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right) \\ &= F w + \sigma [F, A_*] w + \frac{1}{2} \sigma^2 [[F, A_*], A_*] w + \mathcal{O}\left(\tau^4, \|V'\|_{W_\infty^6}, \|w\|_{H^3}\right). \end{aligned}$$

Note also that

$$\left\| e^{-\sigma A_*} (V(t) - V(s)) e^{\sigma A_*} w \right\|_{H^1} = \mathcal{O}\left(\tau, \|V'\|_{W_\infty^1}, \|w\|_{H^1}\right)$$

implies for instance

$$\begin{aligned} \mathcal{I}_4\left(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)\right) w &= \int_0^{\frac{\tau}{2}} \int_0^{\sigma_1} e^{-\sigma_1 A_*} S_2(\tau) e^{\sigma_1 A_*} e^{-\sigma_2 A_*} S_2(\tau) e^{\sigma_2 A_*} d\sigma_2 d\sigma_1 w \\ &= \int_0^{\frac{\tau}{2}} \int_0^{\sigma_1} S_2(\tau) e^{-\sigma_2 A_*} S_2(\tau) e^{\sigma_2 A_*} d\sigma_2 d\sigma_1 w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right) \\ &= \int_0^{\frac{\tau}{2}} \int_0^{\sigma_1} S_2(\tau) S_2(\tau) d\sigma_2 d\sigma_1 w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right). \end{aligned}$$



# Local error (Taylor series expansion)

Obtain expansions

$$\begin{aligned} \mathcal{J}_2(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)) w &= J_2(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^6}, \|w\|_{H^3}\right), \\ \mathcal{J}_2(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) w &= J_2(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^6}, \|w\|_{H^3}\right), \\ J_2(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)) &= I_{21}^{(+)}(S_2) + [I_{22}^{(+)}(S_2), A_*] + [[I_{23}^{(+)}(S_2), A_*], A_*], \\ J_2(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) &= I_{21}^{(+)}(R) + [I_{22}^{(+)}(R), A_*] + [[I_{23}^{(+)}(R), A_*], A_*], \\ \mathcal{J}_4(\cdot, \frac{\tau}{2}, A_*, S_2(\tau)) w &= I_4^{(+)}(S_2) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right), \\ \mathcal{J}_4(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) w &= I_4^{(+)}(R) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right). \end{aligned}$$

# Local error (Taylor series expansion)

Obtain expansions

$$\mathcal{K}_2(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)) w = K_2(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^6}, \|w\|_{H^3}\right),$$

$$\mathcal{K}_2(t_0, \frac{\tau}{2}, A_*, R) w = K_2(t_0, \frac{\tau}{2}, A_*, R) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^6}, \|w\|_{H^3}\right),$$

$$K_2(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)) = I_{21}^{(-)}(S_1) + [I_{22}^{(-)}(S_1), A_*] + [[I_{23}^{(-)}(S_1), A_*], A_*],$$

$$K_2(t_0 + \frac{\tau}{2}, \frac{\tau}{2}, A_*, R) = I_{21}^{(-)}(R) + [I_{22}^{(-)}(R), A_*] + [[I_{23}^{(-)}(R), A_*], A_*],$$

$$\mathcal{K}_4(\cdot, \frac{\tau}{2}, A_*, S_1(\tau)) w = I_4^{(-)}(S_1) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right),$$

$$\mathcal{K}_4(t_0, \frac{\tau}{2}, A_*, R) w = I_4^{(-)}(R) w + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^2}, \|w\|_{H^1}\right).$$

# Local error (Integral representation)

**Local error.** Obtain local error expansion

$$\begin{aligned}
 & \mathcal{S}(\tau) u(t_0) - u(t_0 + \tau) \\
 &= e^{\frac{\tau}{2} A_*} \left( I_{21}^{(+)}(S_2) - I_{21}^{(+)}(R) + [I_{22}^{(+)}(S_2) - I_{22}^{(+)}(R), A_*] + [[I_{23}^{(+)}(S_2) - I_{23}^{(+)}(R), A_*], A_*] \right. \\
 &\quad + I_{21}^{(-)}(S_1) - I_{21}^{(-)}(R) + [I_{22}^{(-)}(S_1) - I_{22}^{(-)}(R), A_*] + [[I_{23}^{(-)}(S_1) - I_{23}^{(-)}(R), A_*], A_*] \\
 &\quad + I_4^{(+)}(S_2) - I_4^{(+)}(R) + I_4^{(-)}(S_1) - I_4^{(-)}(R) \\
 &\quad + \left( I_{21}^{(+)}(S_2) + [I_{22}^{(+)}(S_2), A_*] + [[I_{23}^{(+)}(S_2), A_*], A_*] \right) \\
 &\quad \quad \times \left( I_{21}^{(-)}(S_1) + [I_{22}^{(-)}(S_1), A_*] + [[I_{23}^{(-)}(S_1), A_*], A_*] \right) \\
 &\quad - \left( I_{21}^{(+)}(R) + [I_{22}^{(+)}(R), A_*] + [[I_{23}^{(+)}(R), A_*], A_*] \right) \\
 &\quad \quad \times \left( I_{21}^{(-)}(R) + [I_{22}^{(-)}(R), A_*] + [[I_{23}^{(-)}(R), A_*], A_*] \right) \Big) e^{\frac{\tau}{2} A_*} u(t_0) \\
 &\quad + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^6}, \|u(t_0)\|_{H^3}\right).
 \end{aligned}$$

## Local error (Integrals)

$$I_{21}^{(+)}(S_2) = \int_0^{\frac{\tau}{2}} S_2(\tau) d\sigma_1,$$

$$I_{21}^{(+)}(R) = \int_0^{\frac{\tau}{2}} R(t_0 + \frac{\tau}{2} + \sigma_1) d\sigma_1,$$

$$I_{22}^{(+)}(S_2) = \int_0^{\frac{\tau}{2}} \sigma_1 S_2(\tau) d\sigma_1,$$

$$I_{22}^{(+)}(R) = \int_0^{\frac{\tau}{2}} \sigma_1 R(t_0 + \frac{\tau}{2} + \sigma_1) d\sigma_1,$$

$$I_{23}^{(+)}(S_2) = \frac{1}{2} \int_0^{\frac{\tau}{2}} \sigma_1^2 S_2(\tau) d\sigma_1,$$

$$I_{23}^{(+)}(R) = \frac{1}{2} \int_0^{\frac{\tau}{2}} \sigma_1^2 R(t_0 + \frac{\tau}{2} + \sigma_1) d\sigma_1,$$

$$I_4^{(+)}(S_2) = \int_0^{\frac{\tau}{2}} \int_0^{\sigma_1} S_2(\tau) S_2(\tau) d\sigma_2 d\sigma_1,$$

$$I_4^{(+)}(R) = \int_0^{\frac{\tau}{2}} \int_0^{\sigma_1} R(t_0 + \frac{\tau}{2} + \sigma_1) R(t_0 + \frac{\tau}{2} + \sigma_2) d\sigma_2 d\sigma_1.$$

## Local error (Integrals)

$$I_{21}^{(-)}(S_1) = \int_{-\frac{\tau}{2}}^0 S_1(\tau) d\sigma_1,$$

$$I_{21}^{(-)}(R) = \int_{-\frac{\tau}{2}}^0 R(t_0 + \frac{\tau}{2} + \sigma_1) d\sigma_1,$$

$$I_{22}^{(-)}(S_1) = \int_{-\frac{\tau}{2}}^0 \sigma_1 S_1(\tau) d\sigma_1,$$

$$I_{22}^{(-)}(R) = \int_{-\frac{\tau}{2}}^0 \sigma_1 R(t_0 + \frac{\tau}{2} + \sigma_1) d\sigma_1,$$

$$I_{23}^{(-)}(S_1) = \frac{1}{2} \int_{-\frac{\tau}{2}}^0 \sigma_1^2 S_1(\tau) d\sigma_1,$$

$$I_{23}^{(-)}(R) = \frac{1}{2} \int_{-\frac{\tau}{2}}^0 \sigma_1^2 R(t_0 + \frac{\tau}{2} + \sigma_1) d\sigma_1,$$

$$I_4^{(-)}(S_1) = \int_0^{\frac{\tau}{2}} \int_{\frac{\tau}{2} - \sigma_1}^{\frac{\tau}{2}} S_1(\tau) S_1(\tau) d\sigma_2 d\sigma_1,$$

$$I_4^{(-)}(R) = \int_0^{\frac{\tau}{2}} \int_{\frac{\tau}{2} - \sigma_1}^{\frac{\tau}{2}} R(t_0 + \frac{\tau}{2} - \sigma_1) R(t_0 + \frac{\tau}{2} - \sigma_2) d\sigma_2 d\sigma_1.$$

# Local error ()

**Local error.** In final step, replace  $R$  by Taylor polynomial

$$\begin{aligned}
 & \mathcal{S}(\tau) u(t_0) - u(t_0 + \tau) \\
 &= e^{\frac{\tau}{2} A_*} \left( \underbrace{I_{21}^{(+)}(S_2) - I_{21}^{(+)}(R) + I_{21}^{(-)}(S_1) - I_{21}^{(-)}(R)}_{= \mathcal{O}(\tau^5, R^{(4)})} + \underbrace{[I_{22}^{(+)}(S_2) - I_{22}^{(+)}(R) + I_{22}^{(-)}(S_1) - I_{22}^{(-)}(R), A_*]}_{= \mathcal{O}(\tau^5, R''')} \right) \\
 & \quad + \left[ \underbrace{[I_{23}^{(+)}(S_2) - I_{23}^{(+)}(R) + I_{23}^{(-)}(S_1) - I_{23}^{(-)}(R), A_*]}_{= \mathcal{O}(\tau^5, R'')} \right], A_* \\
 & \quad + \underbrace{[I_4^{(+)}(S_2) - I_4^{(+)}(R) + I_4^{(-)}(S_1) - I_4^{(-)}(R) + I_{21}^{(+)}(S_2) I_{21}^{(-)}(S_1) - I_{21}^{(+)}(R) I_{21}^{(-)}(R)]}_{= c\tau^4 (R')^2} e^{\frac{\tau}{2} A_*} u(t_0) \\
 & \quad + \mathcal{O}\left(\tau^5, \|V'\|_{W_\infty^6}, \|u(t_0)\|_{H^3}\right).
 \end{aligned}$$