

On the reliable and efficient numerical integration of Kuramoto systems on graphs

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References

Recent contribution.

T. BÖHLE, CH. KÜHN, M. TH.

On the reliable and efficient numerical integration of the Kuramoto model and related dynamical systems on graphs.

International Journal of Computer Mathematics (2021).

Dedicated to Jesús María Sanz-Serna due to his seminal contributions in the area of geometric numerical integration.

Currently in preparation.

T. BÖHLE, CH. KÜHN, M. TH.

Community integration algorithms (CIAs) for dynamical systems on graphs.

Guide line

Large-scale classical dynamical systems.

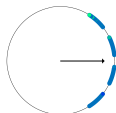
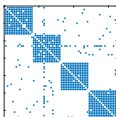
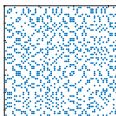
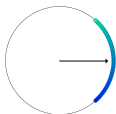
- Algorithms for the evaluation of the defining functions
- Issues and novel approaches

Extended systems on networks / graphs.

- Algorithms for the detection of communities
- Suitable modifications of novel approaches

Widely-used models with relevant applications.

- Classical and extended Kuramoto systems
- Synchronisation of coupled oscillators



Classical Kuramoto systems

**Considerations for classical systems provide the basis for our work.
Classical systems correspond to the special cases of complete graphs.**

Kuramoto systems

Kuramoto systems.

- Consider a **set of oscillators** with time-dependent phases

$$\vartheta_m : [0, T] \longrightarrow \mathbb{S}_1 = \mathbb{R}/2\pi\mathbb{Z}, \quad m \in \{1, 2, \dots, M\}.$$

- Prescribe the intrinsic frequencies and the coupling constant

$$\omega_m \in \mathbb{R}, \quad m \in \{1, 2, \dots, M\}, \quad K > 0.$$

- Describe the **pairwise interactions** between the oscillators by a system of coupled nonlinear ordinary differential equations

$$\begin{cases} \vartheta'_m(t) = \omega_m + \frac{K}{M} \sum_{\ell=1}^M \sin(\vartheta_\ell(t) - \vartheta_m(t)), & t \in (0, T), \\ \vartheta_m(0) \text{ given}, & m \in \{1, 2, \dots, M\}. \end{cases}$$

Kuramoto systems

Large-scale systems.

- Focus on systems involving a **high number of oscillators**

$$M \gg 1.$$

Special choices.

- Consider uniformly distributed initial phases

$$\vartheta_m(0) = \frac{2\pi m}{M}, \quad m \in \{1, 2, \dots, M\}.$$

- Define the intrinsic frequencies by

$$\omega_m = 1 + \omega_0 \frac{(2m-M-1)}{M-1} \in [1 - \omega_0, 1 + \omega_0],$$
$$\omega_0 \geq 0, \quad m \in \{1, 2, \dots, M\},$$

Fundamental issue

Fundamental issue.

- Consider a dynamical system of the form

$$\begin{cases} y'(t) = F(y(t)), & t \in (0, T), \\ y(0) \text{ given.} \end{cases}$$

- Algorithms for the **reliable and efficient evaluation** of the defining function (for fixed $t \in [0, T]$) constitute **basic ingredients** regarding **numerical simulations** (e.g. time integration, optimisation).

Quadratic complexity

Computational complexity.

- For Kuramoto systems, the **naive evaluation** of the decisive sums

$$\sum_{\ell=1}^M \sin(\vartheta_{\ell}(t) - \vartheta_m(t)), \quad m \in \{1, 2, \dots, M\},$$

requires M^2 sine function evaluations.

- Quadratic computational complexity** considerably reduces practicability. Typically, we reach a critical range for

$$M = 10^5, \quad M^2 = 10^{10}.$$

Quadratic complexity

Quadratic complexity.

- It is highly desirable to avoid **quadratic complexity**, since it effects the allocatable memory capacity and the computation time.
- For standard programming and numeric computing platforms, we are confronted with a **severe restriction** of the maximum dimension.

Error message in MATLAB.

Requested 10000000000x1 (74.5GB) array exceeds maximum array size preference. Creation of arrays greater than this limit may take a long time and cause MATLAB to become unresponsive.

Out of memory for a **vector** of dimension 10^{10} .

Out of memory for a **matrix** of dimension 10^5 .

Is a reduction from quadratic to linear complexity feasible?

Quadratic complexity

Natural idea.

- Use a **compact matrix representation** and sum over all columns

$$\begin{pmatrix} s_{11}(t) & s_{12}(t) & \dots & \dots & s_{1M}(t) \\ s_{21}(t) & s_{22}(t) & \dots & \dots & s_{2M}(t) \\ \vdots & & & & \vdots \\ s_{M1}(t) & s_{M2}(t) & \dots & s_{M,M-1}(t) & s_{MM}(t) \end{pmatrix},$$

$$s_{\ell m}(t) = \sin(\vartheta_{\ell}(t) - \vartheta_m(t)), \quad \ell, m \in \{1, 2, \dots, M\},$$

$$\sum_{\ell=1}^M \sin(\vartheta_{\ell}(t) - \vartheta_m(t)) = \sum_{\ell=1}^M s_{\ell m}(t), \quad m \in \{1, 2, \dots, M\}.$$

MATLAB script by Cleve Moler.

% theta-theta' is a matrix with elements theta(j)-theta(k).

% The sum is by columns and produces a column vector.

g = sum(sin(theta-theta'),2);

See <https://blogs.mathworks.com/cleve/2019/10/30/stability-of-kuramoto-oscillators>.

This representation is convenient, but quadratic complexity remains!

Quadratic complexity

Natural idea – modification.

- Omit zero entries and use **anti-symmetry** of sine function

$$s_{\ell m}(t) = \sin(\vartheta_{\ell}(t) - \vartheta_m(t)) = -s_{m\ell}(t), \quad \ell, m \in \{1, 2, \dots, M\},$$

$$\begin{pmatrix} 0 & s_{12}(t) & \dots & \dots & s_{1M}(t) \\ -s_{12}(t) & 0 & s_{23}(t) & \dots & s_{2M}(t) \\ \vdots & & & & \vdots \\ -s_{1M}(t) & \dots & \dots & -s_{M-1,M}(t) & 0 \end{pmatrix}.$$

- Number of sine function evaluations

$$(M-1) + (M-2) + \dots + 2 + 1 \underset{\text{Kleiner Gau\ss}}{=} \frac{1}{2} M(M-1) = \mathcal{O}(M^2).$$

**This representation is useful to recognise a conserved quantity,
 but quadratic complexity still remains!**

Linear complexity

Novel approach.

- Based on the **addition theorem** for the sine function

$$\sin(\vartheta_\ell(t) - \vartheta_m(t)) = \sin(\vartheta_\ell(t)) \cos(\vartheta_m(t)) - \cos(\vartheta_\ell(t)) \sin(\vartheta_m(t)),$$

$$\ell, m \in \{1, 2, \dots, M\},$$

and the **precomputation** of sums

$$S_M(\vartheta(t)) = \sum_{m=1}^M \sin(\vartheta_m(t)), \quad C_M(\vartheta(t)) = \sum_{m=1}^M \cos(\vartheta_m(t)),$$

we obtain a suitable **reformulation** that permits the simultaneous evaluation of the right-hand side and requires **4M** evaluations of sine and cosine functions

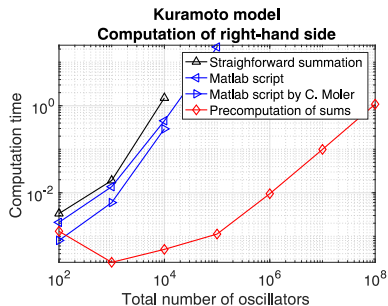
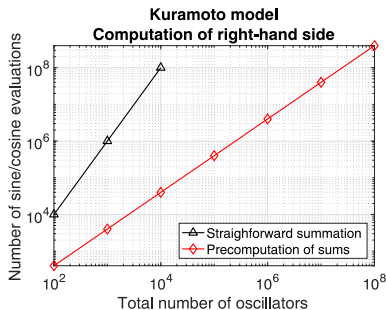
$$\sum_{\ell=1}^M \sin(\vartheta_\ell(t) - \vartheta_m(t)) = S_M(\vartheta(t)) \cos(\vartheta_m(t)) - C_M(\vartheta(t)) \sin(\vartheta_m(t)),$$

$$m \in \{1, 2, \dots, M\}.$$

Numerical simulations

Computational cost for the evaluation of the function defining the right-hand side of the classical Kuramoto model.

- Number of sine and cosine evaluations versus the total number of oscillators when using straightforward summation and the precomputation of sums, respectively.
- Numerical comparison of the computation time for different implementations in MATLAB.



And now we are ready to study structural properties of Kuramoto systems and perform numerical simulations! :-)

Structural properties

Potential.

- Kuramoto systems have the intrinsic structure of **gradient systems**

$$\begin{cases} \vartheta'(t) = -\nabla V(\vartheta(t)), & t \in (0, T), \\ \vartheta(0) \text{ given.} \end{cases}$$

- A compact representation of the associated **potential** reads as

$$V: \mathbb{R}^M \longrightarrow \mathbb{R}:$$

$$\vartheta = (\vartheta_1, \dots, \vartheta_M)^T \longmapsto -\omega^T \vartheta + \frac{KM}{2} \left(1 - (C_M(\vartheta))^2 - (S_M(\vartheta))^2 \right).$$

- A short calculation confirms that the values of the potential indeed decrease when time evolves

$$\frac{d}{dt} V(\vartheta(t)) = \left(\nabla V(\vartheta(t)) \right)^T \vartheta'(t) = -\| \nabla V(\vartheta(t)) \|^2 \leq 0,$$

$$V(\vartheta(t)) \leq V(\vartheta(0)), \quad t \in [0, T].$$

Structural properties

Order parameter.

- The modulus $r : \mathbb{S}_1^M \rightarrow \mathbb{R}$ and the angle $\psi : \mathbb{S}_1^M \rightarrow \mathbb{R}$ of the **complex order parameter** are given by

$$r(\vartheta) e^{i\psi(\vartheta)} = \frac{1}{M} \sum_{m=1}^M e^{i\vartheta_m} = C_M(\vartheta) + i S_M(\vartheta), \quad \vartheta \in \mathbb{S}_1^M.$$

- For configurations, where all cosine and sine values are close-by, the modulus of the complex order parameter has values nearly one and thus **indicates synchronisation**

$$\begin{aligned} \cos(\vartheta_m) &\approx \cos(\vartheta_1), \quad \sin(\vartheta_m) \approx \sin(\vartheta_1), \quad m \in \{2, 3, \dots, M\}, \\ C_M(\vartheta) &\approx \cos(\vartheta_1), \quad S_M(\vartheta) \approx \sin(\vartheta_1), \\ r(\vartheta) &= \sqrt{(C_M(\vartheta))^2 + (S_M(\vartheta))^2} \approx 1, \quad V(\vartheta) \approx -\omega^T \vartheta, \quad \vartheta \in \mathbb{S}_1^M. \end{aligned}$$

Structural properties

Conserved quantity.

- From the representation

$$\begin{cases} \vartheta'_m(t) = \omega_m + \frac{K}{M} \sum_{\ell=1}^M s_{\ell m}(t), & t \in (0, T), \\ \vartheta_m(0) \text{ given, } & m \in \{1, 2, \dots, M\}, \end{cases}$$

$$\begin{pmatrix} 0 & s_{12}(t) & \dots & \dots & s_{1M}(t) \\ -s_{12}(t) & 0 & s_{23}(t) & \dots & s_{2M}(t) \\ \vdots & & & & \vdots \\ -s_{1M}(t) & \dots & \dots & -s_{M-1,M}(t) & 0 \end{pmatrix}, \quad t \in (0, T),$$

it is evident that summation over all governing equations (i.e. all entries of the associated matrix) and integration with respect to time yields

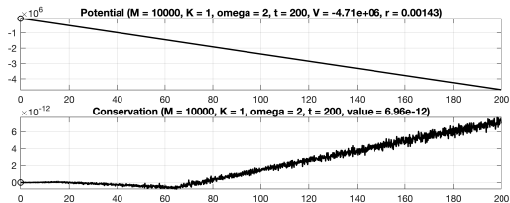
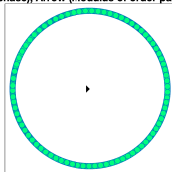
$$\frac{1}{M} \sum_{m=1}^M \vartheta'_m(t) = \frac{1}{M} \sum_{m=1}^M \omega_m, \quad \frac{1}{M} \sum_{m=1}^M \vartheta_m(t) = \frac{1}{M} \sum_{m=1}^M \vartheta_m(0) + t \frac{1}{M} \sum_{m=1}^M \omega_m, \quad t \in [0, T].$$

- Thus, the mean values of the initial phases and the intrinsic frequencies determine the mean values of the phases at later times.

Numerical simulations (no synchronisation)

Numerical integration of the classical Kuramoto model involving $M = 10^4$ oscillators. Coupling constant $K = 1$ (no synchronisation). Visualisation of the phases at the final time. The time series confirms decreasing potential values. A conserved quantity is numerically preserved with high accuracy.

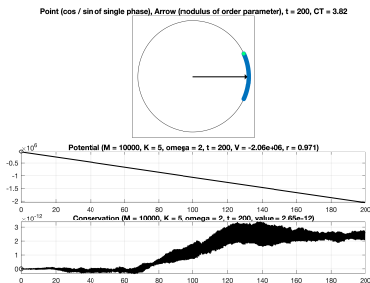
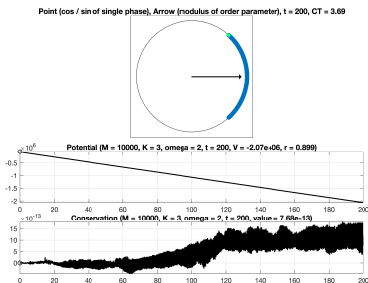
Point (cos / sin of single phase), Arrow (modulus of order parameter), $t = 200$, $CT = 3.79$



<http://techmath.uibk.ac.at/mecht/MyHomepage/Research/MovieKuramotoClassicalK1.m4v>

Numerical simulations (gradual synchronisation)

Numerical integration of the classical Kuramoto model involving $M = 10^4$ oscillators.
Coupling constant $K \in \{3, 5\}$ (gradual synchronisation).



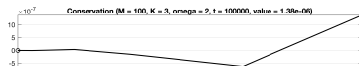
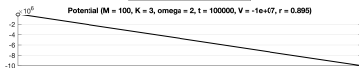
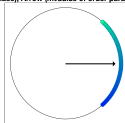
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<http://techmath.uibk.ac.at/mecht/MyHomepage/Research/MovieKuramotoClassicalK5.m4v>

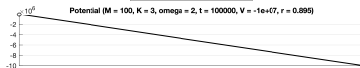
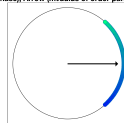
Numerical simulations (long-term integration)

Long-term integration of the classical Kuramoto model based on a second-order explicit Runge–Kutta method and a second-order implicit Runge–Kutta method with improved numerical preservation of a conserved quantity.

Point (cos / sin of single phase), Arrow (modulus of order parameter, $t = 100000$, $CT = 29.4$)



Point (cos / sin of single phase), Arrow (modulus of order parameter, $t = 100000$, $CT = 77.2$)



Higher-order Kuramoto-type systems

Higher-order Kuramoto-type systems

Higher-order contributions.

- Single sums describe **pairwise interactions between oscillators**

$$\frac{1}{M} \sum_{\ell=1}^M \sin(\vartheta_{\ell}(t) - \vartheta_m(t)), \quad m \in \{1, 2, \dots, M\}.$$

- Multiple sums describe **interactions between several oscillators**

$$\frac{1}{M^L} \sum_{\ell_1, \dots, \ell_L=1}^M \sin(\sigma_1 \vartheta_{\ell_1}(t) + \dots + \sigma_L \vartheta_{\ell_L}(t) - \vartheta_m(t)),$$
$$\sigma_1, \dots, \sigma_L \in \{-1, 1\}, \quad m \in \{1, \dots, M\}.$$

Polynomial complexity

Computational complexity.

- The **naive evaluation** of single sums

$$\sum_{\ell=1}^M \sin(\vartheta_{\ell}(t) - \vartheta_m(t)), \quad m \in \{1, 2, \dots, M\},$$

requires $\mathcal{O}(M^2)$ sine function evaluations.

- The **naive evaluation** of multiple sums

$$\frac{1}{M^L} \sum_{\ell_1, \dots, \ell_L=1}^M \sin(\sigma_1 \vartheta_{\ell_1}(t) + \dots + \sigma_L \vartheta_{\ell_L}(t) - \vartheta_m(t)),$$
$$\sigma_1, \dots, \sigma_L \in \{-1, 1\}, \quad m \in \{1, \dots, M\}.$$

requires $\mathcal{O}(M^{L+1})$ sine function evaluations.

Is a reduction from polynomial to linear complexity feasible? YES!

Linear complexity

Novel approach.

- Based on the **addition theorem** for the sine function and the **precomputation** of sums

$$S_M(\vartheta(t)) = \sum_{m=1}^M \sin(\vartheta_m(t)), \quad C_M(\vartheta(t)) = \sum_{m=1}^M \cos(\vartheta_m(t)),$$

we obtain a suitable **reformulation** that permits the simultaneous evaluation of the right-hand side and requires $\mathcal{O}(M)$ evaluations of sine and cosine functions.

Example ($L = 3$). With $S_M = S_M(\vartheta)$ and $C_M = C_M(\vartheta)$, the multiple sums rewrite as

$$\begin{aligned} & \sum_{\ell_1, \ell_2, \ell_3=1}^M \sin(\sigma_1 \vartheta_{\ell_1} + \sigma_2 \vartheta_{\ell_2} + \sigma_3 \vartheta_{\ell_3} - \vartheta_m) \\ &= \left((\sigma_1 + \sigma_2 + \sigma_3) C_M^2 - \sigma_1 \sigma_2 \sigma_3 S_M^2 \right) S_M \cos(\vartheta_m) \\ & \quad + \left((\sigma_1 \sigma_2 + \sigma_1 \sigma_3 + \sigma_2 \sigma_3) S_M^2 - C_M^2 \right) C_M \sin(\vartheta_m(t)), \quad m \in \{1, \dots, M\}. \end{aligned}$$

Summary

Computational complexity. It is reasonable to measure the **cost** for the evaluation of the defining functions of classical Kuramoto systems and generalisations involving terms of order L by the **number of sine and cosine function evaluations** in dependence of the total number of oscillators.

- A naive formulation results in **polynomial complexity**.
- Suitable reformulations and precomputations of sums permit the reduction to **linear complexity**.

	Naive approach	Novel approach
Classical Kuramoto systems	$\mathcal{O}(M^2)$	$\mathcal{O}(M)$
Higher-order generalisations	$\mathcal{O}(M^{L+1})$	$\mathcal{O}(M)$

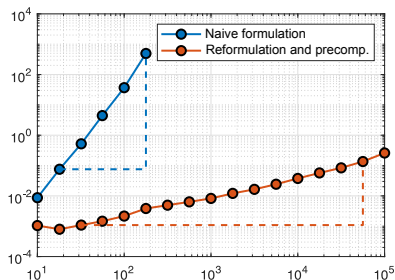
Numerical simulations

Numerical integration of a higher-order Kuramoto-type system involving a term of the form

$$\sum_{\ell_1, \ell_2, \ell_3=1}^M \sin(\vartheta_{\ell_1} - \vartheta_{\ell_2} + \vartheta_{\ell_3} - \vartheta_m) = \left(C_M^2 + S_M^2 \right) \left(S_M \cos(\vartheta_m) - C_M \sin(\vartheta_m(t)) \right), \quad m \in \{1, \dots, M\}.$$

Computation times in seconds versus the dimensions of the system.

- A naive formulation and implementation leads to quartic complexity $\mathcal{O}(M^4)$.
- A suitable reformulation and the precomputation of sums permit the reduction to linear complexity $\mathcal{O}(M)$.



Kuramoto systems on graphs

**A picture says more than a thousand words ...
... rigorous formulas are found in our papers.**

Kuramoto systems on graphs

Kuramoto systems on graphs.

- Take into account **pairwise interactions** between **certain oscillators**.
- Build up the associated **adjacency matrix**

$$A = (A_{m\ell})_{\ell, m \in \{1, \dots, M\}},$$

$$\begin{cases} \text{Interaction between oscillators } \ell \text{ and } m: & A_{m\ell} = 1, \\ \text{No interaction between oscillators } \ell \text{ and } m: & A_{m\ell} = 0, \\ & \ell, m \in \{1, 2, \dots, M\}. \end{cases}$$

Kuramoto systems on graphs

Kuramoto systems on graphs.

- The resulting system of coupled nonlinear ordinary differential equations has the form

$$\begin{cases} \vartheta'_m(t) = \omega_m + \frac{K}{\mathcal{M}_m} \sum_{\ell=1}^M A_{m\ell} \sin(\vartheta_\ell(t) - \vartheta_m(t)), & t \in (0, T), \\ \vartheta_m(0) \text{ given, } & m \in \{1, 2, \dots, M\}. \end{cases}$$

- Common uniform scaling

$$\mathcal{M}_m = M, \quad m \in \{1, 2, \dots, M\}.$$

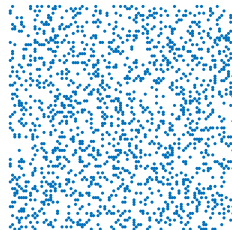
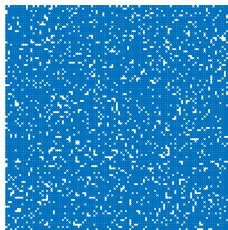
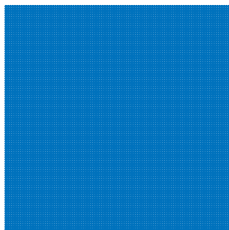
- Alternative non-uniform scaling

$$\mathcal{M}_m = \sum_{\ell=1}^M A_{m\ell}, \quad m \in \{1, 2, \dots, M\}.$$

Kuramoto systems on graphs

Kuramoto systems on graphs.

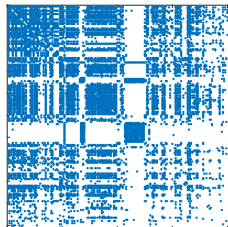
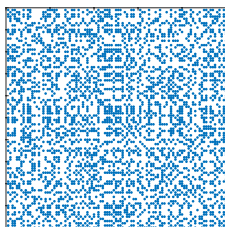
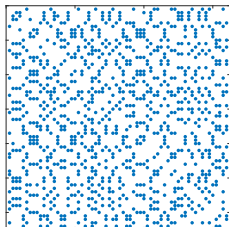
- A **full matrix** corresponds to a **classical system** (all-to-all coupling).
- A relatively **dense matrix** reflects relatively **many interactions** between the oscillators.
- A relatively **sparse matrix** reflects relatively **few interactions** between the oscillators.



Kuramoto systems on graphs

Realistic situations.

- Randomly generated **adjacency matrices** studied in the context of **Kuramoto systems on graphs**.
- Adjacency matrix associated with a **real data graph for animal networks** studied in the context of Cucker–Smale systems.



See <https://networkrepository.com/aves-wildbird-network.php>.

Computational complexity

Computational complexity.

- The number of **non-zero coefficients** determines the **computational complexity** (required memory capacity, computation time).

Natural questions.

- Is there an **alternative approach** to the **straightforward summation** of contributions corresponding to non-zero coefficients?

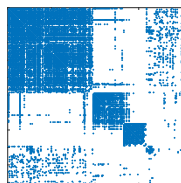
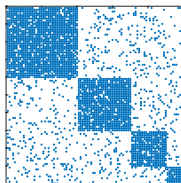
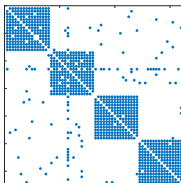
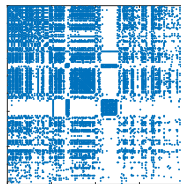
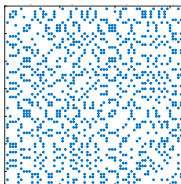
$$\sum_{\substack{\ell=1 \\ A_{m\ell} \neq 0}}^M \sin(\vartheta_\ell(t) - \vartheta_m(t)), \quad m \in \{1, 2, \dots, M\}.$$

- Is there a possibility to use the **underlying structure** of the **graph**?

Key idea (pre-simulation step)

Community detection.

- Transform the underlying adjacency matrix (first row) by a permutation matrix to a **block matrix** (second row).



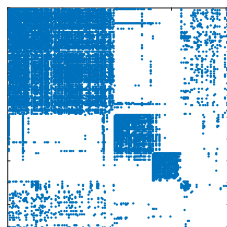
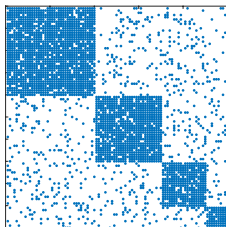
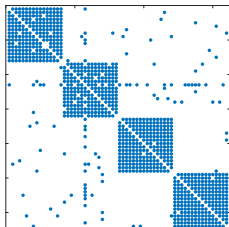
Key idea (pre-simulation step)

Identification of submatrices.

- Identify relatively dense and relatively sparse submatrices.

Simple test case (left).

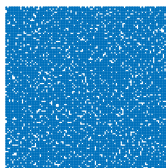
- Four communities of oscillators. Numerous pairwise interactions within each community and few pairwise interactions otherwise.



Key idea (evaluation step)

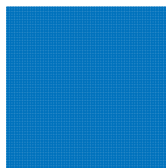
Evaluation of defining function.

- For a **relatively dense submatrix**, the **main component** corresponds to a **classical subsystem**, which is resolved in an efficient manner by precomputations (see first part of the talk). The contributions of zero coefficients are compensated.



dense submatrix

=



full matrix

-



sparse submatrix

- For a **relatively sparse submatrix**, the straightforward summation of non-zero coefficients is used.

Numerical simulations

General setting. Time integration of Kuramoto systems on graphs.

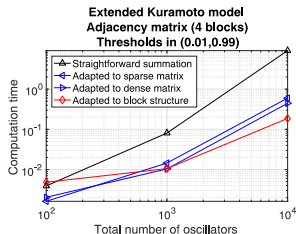
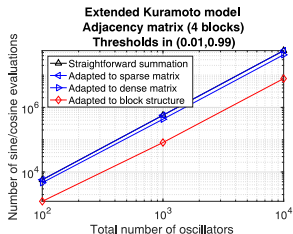
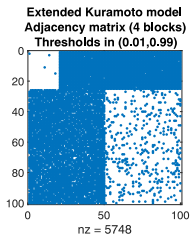
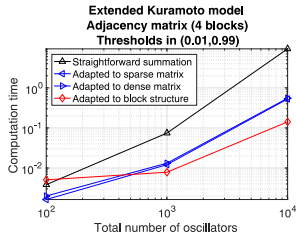
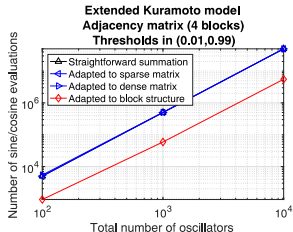
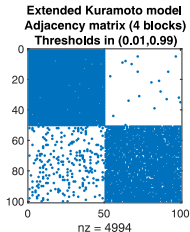
Specific setting. Random generation of adjacency matrices through certain thresholds per block. Evaluation of the defining functions by straightforward summation or approaches adapted to sparse matrices, dense matrices, and block matrices.

- Illustration of the adjacency matrix.
- Comparison of the numbers of sine and cosine evaluations versus the total numbers of oscillators.
- Comparison of the computation times.

Observations. The obtained results confirm that the **novel approach** is **beneficial** for a **higher number of oscillators**, where the evaluation of functions and the computation of sums are expected to be the most time consuming components.

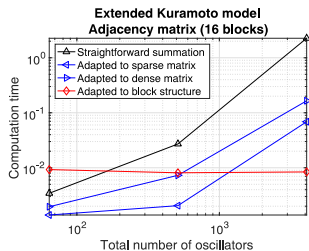
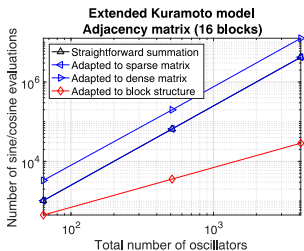
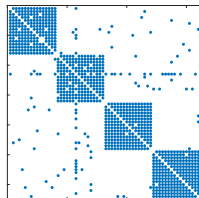
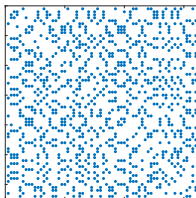
Numerical simulations

Block matrices involving two dense blocks.



Numerical simulations

Block matrix involving four dense blocks. A more realistic adjacency matrix describes the interactions of four communities of oscillators.

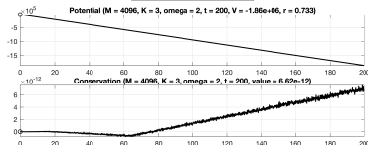
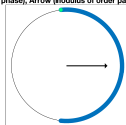


Numerical simulations

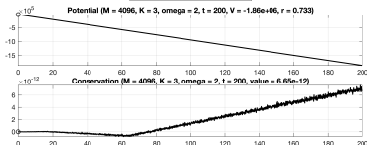
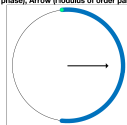
Numerical integration of a Kuramoto model on a graph comprising four communities.
 Consideration of the common uniform scaling.

- Evaluation of the right-hand side by straightforward summation.
- Employing the block structure of the associated adjacency matrix and using the precomputation of sums permits a **significant reduction** of the computation time!

Point (cos / sin of single phase), Arrow (modulus of order parameter), $t = 200$, $CT = 688$



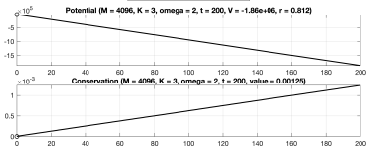
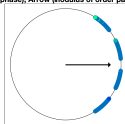
Point (cos / sin of single phase), Arrow (modulus of order parameter), $t = 200$, $CT = 53.6$



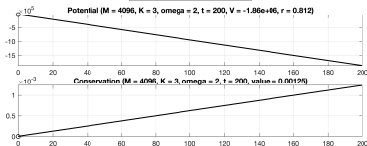
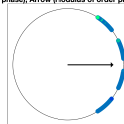
Numerical simulations

Corresponding results for a non-uniform scaling. Synchronisation within four communities is observed. Due to the lack of symmetry of the system, the conservation property does not hold. Again, the computation time is **significantly reduced**.

Point (cos / sin of single phase), Arrow (modulus of order parameter), $t = 200$, CT = 728



Point (cos / sin of single phase), Arrow (modulus of order parameter), $t = 200$, CT = 50.9



Summary and open questions

Summary.

- A novel approach for the reliable and efficient evaluation of the defining functions permits numerical simulations for large-scale dynamical systems on graphs.

Open questions.

- Suitable approximations of the defining functions to enhance general applicability.

Thank you!